# PERTURBATION OF NORMAL QUATERNIONIC OPERATORS 

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Abstract. The theory of quaternionic operators has applications in several different fields, such as quantum mechanics, fractional evolution problems, and quaternionic Schur analysis, just to name a few. The main difference between complex and quaternionic operator theory is based on the definition of a spectrum. In fact, in quaternionic operator theory the classical notion of a resolvent operator and the one of a spectrum need to be replaced by the two $S$-resolvent operators and the $S$-spectrum. This is a consequence of the noncommutativity of the quaternionic setting. Indeed, the $S$-spectrum of a quaternionic linear operator $T$ is given by the noninvertibility of a second order operator. This presents new challenges which make our approach to perturbation theory of quaternionic operators different from the classical case. In this paper we study the problem of perturbation of a quaternionic normal operator in a Hilbert space by making use of the concepts of $S$-spectrum and of slice hyperholomorphicity of the $S$-resolvent operators. For this new setting we prove results on the perturbation of quaternionic normal operators by operators belonging to a Schatten class and give conditions which guarantee the existence of a nontrivial hyperinvariant subspace of a quaternionic linear operator.

## 1. Introduction

The spectral theory for quaternionic linear operators and, as a particular case, for vector operators, has been an open problem for a long time because the notion of a spectrum of a quaternionic linear operator was unclear. Indeed, the notions of left or right spectrum of a quaternionic linear operator are not suitable to develop a full theory. This situation changed a decade ago when the new notion of an $S$-spectrum was introduced; see the book [16].

There are several reasons to study quaternionic spectral theory, and below we mention some of them. First of all there is interest coming from the study of partial differential equations (PDEs) (or more generally of pseudo-differential operators) over noncommutative structures. Much attention has been given to the case of nilpotent Lie groups, which has been studied since the 1970s (see [22, 38]). This is due to the fact that the corresponding Baker-Campbell-Hausdorff formula is then finite (that is to say, the higher order commutators are 0 after a finite order), which allows for an easier theory. Even more challenging are PDEs

[^0]and pseudo-differential operators over other structures like quaternions, where the Baker-Campbell-Hausdorff formula exhibits only a periodic nature (higher order commutators are equal to lower order commutators after a finite order), are being considered since these cases are obviously more complicated. The case of quaternions is even more important since they are closely linked to symmetries in the phase space and, therefore, the corresponding PDEs also have close connections with both time-frequency analysis and quantum mechanics. In a celebrated paper [9] Birkhoff and von Neumann showed that quantum mechanics can be written only in the real, complex, or quaternionic setting. This fact stimulated a number of works, among which we mention [1, 20, 21, 29]. Recently (see [4, 7]), the spectral theorem based on the $S$-spectrum for quaternionic normal operators was proved. This provides the grounds to study quantum mechanics in the quaternionic setting. Recently, the equivalence of complex and quaternionic quantum mechanics has been treated in [24].

Another question which was recently solved was to find a quaternionic analogue of the Riesz-Dunford functional calculus of the complex setting. This calculus can be naturally extended to quaternionic operators using the theory of slice hyperholomorphic functions, the $S$-spectrum, and the $S$-resolvent operators, which are crucial objects to properly defining the quaternionic functional calculus, also called $S$-functional calculus; see the books [16,17] and [3, 23]. This calculus allows one to study the theory of quaternionic evolution operators, which was developed in [2. 6, 14]. We also point out that the $S$-resolvent operators naturally appear in the realization of quaternionic Schur functions, which has allowed a rapid development of Schur analysis in the slice hyperholomorphic setting; see the book [5].

More recently, it turned out that quaternionic spectral theory is also a useful tool to study new classes of fractional evolution problems. In fact, using the quaternionic version of the $H^{\infty}$ functional calculus, one can define fractional powers of vector operators and obtain a new approach to fractional diffusion processes; see [8, 11, 12 ] for more details.

The above facts provide sound motivations to consider the perturbation theory of quaternionic linear operators, whose investigation is alive even in the classic complex, e.g., in 33-35].

To understand the additional difficulties compared to the classical case which arise in a noncommutative setting, we now discuss some of the main differences between classical spectral theory and the spectral theory based on the $S$-spectrum. Let us begin by recalling that, given a bounded complex linear operator $A$ acting on a complex Banach space $X$, its spectrum is defined by

$$
\sigma(A)=\{\lambda \in \mathbb{C}: \lambda \mathcal{I}-A \text { is not invertible }\}
$$

For $\lambda$ in the resolvent set $\rho(A):=\mathbb{C} \backslash \sigma(A)$ the resolvent operator $(\lambda \mathcal{I}-A)^{-1}$ is a holomorphic function with values in the Banach space $\mathcal{B}(X)$ of all bounded linear operators on $X$ endowed with the natural norm. Now let us consider a bounded linear operator defined on a two sided quaternionic Banach space $V$; given a quaternionic operator $T$, one has to specify on which side the linearity is considered. In this paper we consider right linearity, but, for the sake of simplicity, in this introduction we will simply write "quaternionic linear operator" without specifying the type of linearity where it is not needed. The operator $s \mathcal{I}-T$ acts on a vector $v \in V$ as $s v-T v$, while $\mathcal{I} s-T$ acts on a vector $v \in V$ as $v s-T v$. The first operator is right linear over $\mathbb{H}$, while the second is not. We note also that the first
operator, though linear, does not seem to have any physical meaning, while the second gives the notion of right eigenvalues, which is widely used in physics and in linear algebra over noncommutative structures. Moreover, the inverse of both the operators above is not associated with any notion of hyperholomorphy. For these reasons, in the quaternionic setting the appropriate notion of spectrum is the one of the $S$-spectrum, which is defined by a second order operator. Specifically, the $S$-spectrum of a quaternionic linear operator $T$ is defined as

$$
\sigma_{S}(T)=\left\{s \in \mathbb{H}: T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I} \text { is not invertible }\right\}
$$

where $\mathbb{H}$ denotes the algebra of quaternions, $\operatorname{Re}(s)$ is the real part of the quaternion $s$, and $|s|^{2}$ is the square of its Euclidean norm. It is important to note that the point $S$-spectrum coincides with the set of right eigenvalues (see [15, 25]); thus the operator $Q_{s}(T):=\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}\right)^{-1}$, called the pseudo-resolvent operator, is the linear operator associated with the notion of right eigenvalues. The operator $\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}\right)^{-1}$ is defined on the $S$-resolvent set $\rho_{S}(T):=\mathbb{H} \backslash \sigma_{S}(T)$, and it is a continuous function with values in the space $\mathcal{B}(V)$ of all bounded quaternionic linear operators, but it is not hyperholomorphic with respect to any known notion of hyperholomorphicity. To define the analogue of the resolvent operator $(\lambda \mathcal{I}-A)^{-1}$ with some analyticity properties, denote by $\bar{s}$ the conjugate of the quaternion $s$. We define the $S$-resolvent operators as

$$
S_{L}^{-1}(s, T):=-Q_{s}(T)(T-\bar{s} \mathcal{I})
$$

and

$$
S_{R}^{-1}(s, T):=-(T-\bar{s} \mathcal{I}) Q_{s}(T)
$$

These operators defined on $\rho_{S}(T)$ are right- and left-slice hyperholomorphic operatorvalued functions, respectively, where the notions of left- and right-slice hyperholomorphic functions will be defined in the sequel. Thus in the quaternionic setting there are two resolvent operators, $S_{L}^{-1}(s, T)$ and $S_{R}^{-1}(s, T)$, and, moreover, the $S$-resolvent equation involves both of the $S$-resolvent operators; see Section 2 for more details. Using the notion of slice hyperholomorphic functions we can define the analogue of the Riesz-Dunford functional calculus for quaternionic operators, and in a natural way we can define the Riesz-projectors; see [3].

We also want to point out that there exist other approaches to functional calculi in higher dimensions. In a series of papers - see, for example, 30-32, 37-McIntosh and coauthors introduced and studied the functional calculus for $n$-tuples of operators using the more classical theory of monogenic functions. In this theory one introduces a different notion of spectrum based on the Cauchy integral formula for monogenic functions. This theory, however, lacks the appropriate tools for the study of perturbations of normal operators such as the lack of a spectral theorem.

The literature contains a great amount of works on invariant subspaces of operators in a Hilbert space; without claiming completeness, we mention as examples the works of Livsic [36], Brodskii 10, Sz.-Nagy et al. 41], and Gohberg and Krein [27, 28] and the references therein. In this paper we consider the problem of the perturbation of normal operators in a Hilbert space and the existence of (hyper)invariant subspaces for quaternionic normal operators. The classic results in the complex case can be found in the book [39] by Radjavi and Rosenthal. The knowledge of invariant subspaces gives information on the structure of operators; however, they do not always exist: there exist bounded linear operators on a complex inner-product space without a nontrivial invariant subspace. We are going to
study compact perturbations of normal operators on a quaternionic Hilbert space whose spectrum lies on a smooth Jordan arc for specific two-dimensional subspaces, later called slices. From these perturbation results one can deduce, under suitable assumptions, the existence of invariant subspaces. We also discuss the existence of hyperinvariant subspaces, which are related to the structure of the so-called commutant of $T$, namely the set of operators commuting with $T$. We work in a class of vector-valued slice hyperholomorphic functions that have a slice hyperholomorphic continuation across arcs contained in the $S$-spectrum of the operators intersected with a complex plane. As we shall see, this is not reductive, provided the symmetry properties on the $S$-spectrum.

It is necessary to point out that the noncommutative setting of quaternions involves several challenges from the technical side. If one looks at the classic proofs in [39], one can easily see that they are heavily dependent on the commutativity of the underlying complex field. For example, in the complex case, given a linear operator $A$, any linear operator $B$ commuting with $A$ also commutes with the resolvent $(\lambda \mathcal{I}-A)^{-1}$. In the quaternionic case, a right linear operator $B$ commuting with a given right linear operator $T$ does not commute, in general, with the $S$ resolvent operators because it does not commute with the quaternionic variable. It does commute with the pseudo resolvent since it has only real coefficients, but as we have discussed, this operator does not have any analyticity property. Additionally, in the quaternionic setting one has to face the fact that the algebraic inverse of the (nonlinear) operator $T-\mathcal{I} s$, the operator which gives the spectrum (the pseudo resolvent $\left.Q_{s}(T)\right)$ and the two $S$-resolvent operators correspond to four different operators. As a matter of fact, the algebraic inverse plays no role. The pseudo resolvent and the two $S$-resolvent operators are all required for the proofs of the various results. Furthermore, the two $S$-resolvent operators cannot simply be used in an arbitrary order. This also allows us to demonstrate the properties which are really required in the quaternionic setting.

The plan of the paper is as follows. In Section 2 we introduce the splitting of the $S$-spectrum in an approximate point $S$-spectrum and compression $S$-spectrum, and we show some related results; moreover, we give a quick overview of the $S$-functional calculus. Section 3 contains some results related with quaternionic normal operators. In Section 4 we show some results on the Schatten class of quaternionic normal operators. In Section 5 we state and prove our main results on the perturbation of normal operators and some consequences. More specifically, we prove results which guarantee the existence of a nontrivial (hyper)invariant subspace of a quaternionic linear operator $T$, and we discuss some consequences.

## 2. Preliminary results on quaternionic bounded operators

This section contains, besides some preliminaries, new results on the properties of the splitting of the $S$-spectrum of a quaternionic linear operator of $T$ in terms of the approximate point $S$-spectrum $\Pi_{S}(T)$ and the compression $S$-spectrum $\Gamma_{S}(T)$ of $T$. Finally, we recall the $S$-functional calculus.

We denote by $\mathbb{H}$ the algebra of quaternions. The imaginary units in $\mathbb{H}$ are denoted by $e_{1}, e_{2}, e_{3}$, they satisfy the relations $e_{1}^{2}=e_{2}^{2}=e_{3}^{2}=-1, e_{1} e_{2}=-e_{2} e_{1}=e_{3}$, $e_{2} e_{3}=-e_{3} e_{2}=e_{1}, e_{3} e_{1}=-e_{1} e_{3}=e_{2}$, and an element in $\mathbb{H}$ is of the form $q=x_{0}+e_{1} x_{1}+e_{2} x_{2}+e_{3} x_{3}$ for $x_{\ell} \in \mathbb{R}$. The real part, the imaginary part, and the modulus of a quaternion are defined as $\operatorname{Re}(q)=x_{0}, \operatorname{Im}(q)=e_{1} x_{1}+e_{2} x_{2}+e_{3} x_{3}$,
and $|q|^{2}=x_{0}^{2}+x_{1}^{2}+x_{2}^{2}+x_{3}^{2}$, respectively. The conjugate of the quaternion $q=$ $x_{0}+e_{1} x_{1}+e_{2} x_{2}+e_{3} x_{3}$ is defined by

$$
\bar{q}=\operatorname{Re}(q)-\operatorname{Im}(q)=x_{0}-e_{1} x_{1}-e_{2} x_{2}-e_{3} x_{3} .
$$

Let us denote by $\mathbb{S}$ the unit sphere of purely imaginary $\mathbb{S}$ quaternions, i.e.,

$$
\mathbb{S}=\left\{q=e_{1} x_{1}+e_{2} x_{2}+e_{3} x_{3} \text { such that } x_{1}^{2}+x_{2}^{2}+x_{3}^{2}=1\right\}
$$

Given a nonreal quaternion $q=x_{0}+\operatorname{Im}(q)=x_{0}+\mathbb{J}|\operatorname{Im}(q)|, \mathbb{J}=\operatorname{Im}(q) /|\operatorname{Im}(q)| \in \mathbb{S}$, we can associate with it the two-dimensional sphere defined by

$$
[q]=\left\{x_{0}+\mathbb{J}|\operatorname{Im}(q)|: \mathbb{J} \in \mathbb{S}\right\}
$$

We also need the notion of slice hyperholomorphicity, which will replace the notion of analyticity in the functional calculus. Let us start with the notion of axially symmetric domains.

Definition 2.1. Let $U \subseteq \mathbb{H}$ be an open set. We say that $U$ is axially symmetric if, for all $u+\mathbb{J} v \in U$, the whole 2 -sphere $[u+\mathbb{J v}]$ is contained in $U$.

The above notion allows us to introduce the notion of slice hyperholomorphicity for functions defined over axially symmetric domains.

Definition 2.2 (Slice hyperholomorphic functions). Let $U \subseteq \mathbb{H}$ be an axially symmetric open set, and let $\mathcal{U} \subseteq \mathbb{R} \times \mathbb{R}$ be such that $q=u+\mathbb{J} v \in U$ for all $(u, v) \in \mathcal{U}$. We say that a function on $U$ of the form

$$
f(q)=\alpha(u, v)+\mathbb{J} \beta(u, v)
$$

is left-slice hyperholomorphic if $\alpha, \beta$ are $\mathbb{H}$-valued differentiable functions such that

$$
\alpha(u, v)=\alpha(u,-v), \quad \beta(u, v)=-\beta(u,-v) \quad \text { for all }(u, v) \in \mathcal{U}
$$

and if $\alpha$ and $\beta$ satisfy the Cauchy-Riemann system

$$
\partial_{u} \alpha-\partial_{v} \beta=0, \quad \partial_{v} \alpha+\partial_{u} \beta=0
$$

When $f$ is of the form

$$
f(q)=\alpha(u, v)+\beta(u, v) \mathbb{J}
$$

with the above properties for $\alpha$ and $\beta$, we say that $f$ is a right-slice hyperholomorphic function on $U$. The set of left- (resp., right-) slice hyperholomorphic functions on $U$ will be denoted by $\mathcal{S H}_{L}(U)$ (resp., $\mathcal{S H}_{R}(U)$ ). Slice hyperholomorphic functions on $U$ such that $\alpha(u, v)$ and $\beta(u, v)$ are real valued are called intrinsic, and the corresponding set is denoted by $\mathcal{N}(U)$.

Definition 2.3. Let $U \subseteq \mathbb{H}$ be an axially symmetric open set, and let $f, g: U \rightarrow \mathbb{H}$ be left-slice hyperholomorphic functions. Let $f(x+\mathbb{J} y)=\alpha(x, y)+\mathbb{J} \beta(x, y)$, and let $g(x+\mathbb{J} y)=\gamma(x, y)+\mathbb{J} \delta(x, y)$. Then we define a $\star_{l}$-product as

$$
\begin{equation*}
\left(f \star_{l} g\right)(x+\mathbb{J} y):=(\alpha \gamma-\beta \delta)(x, y)+\mathbb{J}(\alpha \delta+\beta \gamma)(x, y) \tag{2.1}
\end{equation*}
$$

It can be easily verified that, by its construction, the function $f \star_{l} g$ is left-slice hyperholomorphic. A similar multiplication can be defined in the case of right-slice hyperholomorphic functions, and it is denoted by $\star_{r}$, according to the position of $\mathbb{J}$. When it is not needed to distinguish the two cases, we will simply write $\star$.

Remark 2.4. The above notions of slice hyperholomorphicity and $\star$-multiplication can be extended to operator-valued functions; see [5]. We can also define a notion of the inverse of a function with respect to the $\star$-product (see, e.g., [5]), but since we do not need it in its full generality, we introduce it just for the case we will need, namely the $\star$-inverse of the function $f(q)=q-s$, which is both left and right hyperholomorphic in $q$. We have

$$
\begin{aligned}
& (q-s)^{-\star_{l}}=\left(q^{2}-2 \operatorname{Re}(s) q+|s|^{2}\right)^{-1}(q-\bar{s}) \\
& (q-s)^{-\star_{r}}=(q-\bar{s})\left(q^{2}-2 \operatorname{Re}(s) q+|s|^{2}\right)^{-1}
\end{aligned}
$$

We note that $g(s)=q-s$ is left- and right-slice hyperholomorphic in $s$, and we can construct its left and right $\star$-inverses in the variable $s$. These inverses are related to the inverses $f^{-\star_{l}}, f^{-\star_{r}}$ computed in $q$ as follows since (see, e.g., [16]) the following identities hold:

$$
\begin{aligned}
f^{-\star_{l}}(q) & =\left(q^{2}-2 \operatorname{Re}(s) q+|s|^{2}\right)^{-1}(q-\bar{s}) \\
& =-(s-\bar{q})\left(s^{2}-2 \operatorname{Re}(q) s+|q|^{2}\right)^{-1}=-g^{-\star_{r}}(s) \\
f^{-\star_{r}}(q) & =(q-\bar{s})\left(q^{2}-2 \operatorname{Re}(s) q+|s|^{2}\right)^{-1} \\
& =-\left(s^{2}-2 \operatorname{Re}(q) s+|q|^{2}\right)^{-1}(s-\bar{q})=-g^{-\star_{l}}(s) .
\end{aligned}
$$

Slice hyperholomorphic functions are those functions for which the $S$-functional calculus can be defined, as we will see in the sequel.

Now let $V$ be a right vector space on $\mathbb{H}$. In the sequel we will consider right linear operators on $V$, and we will denote by $\mathcal{B}(V)$ the quaternionic Banach space of all right linear bounded operators endowed with the natural norm. Furthermore, a vector space $V$ which is a quaternionic Hilbert space will be denoted by $\mathcal{H}$.

Since the standard generalization of the notion of spectrum as well as the question of solvability of the equation $T v-v s=0$ leads to discussions of invertibility of a nonlinear operator, we are going to use the following notion of the $S$-spectrum, which reduces the question to the invertibility of a second order scalar (with respect to the underlying algebra) operator.

Definition 2.5. Let $T \in \mathcal{B}(V)$. We define the $S$-spectrum of $T$ as

$$
\sigma_{S}(T)=\left\{s \in \mathbb{H}: T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I} \text { is not invertible }\right\},
$$

and we define the $S$-resolvent set of $T$ as

$$
\rho_{S}(T)=\mathbb{H} \backslash \sigma_{S}(T)
$$

Hereby, the second order operator

$$
Q_{s}(T):=\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}\right)^{-1}, \quad s \in \rho_{S}(T)
$$

will be called the pseudo-resolvent operator.
While we have the natural notion of the pseudo-resolvent $Q_{s}(T)$, this does not give a good replacement of the classic resolvent operator $(A-\lambda \mathcal{I})^{-1}$ alone since it originates from a second order operator. In fact, for the actual study of the operator $T$ we also need the notion of the $S$-resolvent operator which can be defined in a left- and a right-form. As will be clear in the sequel, only the interplay of all three operators will provide an adequate replacement of the classic resolvent operator.
Definition 2.6. Let $T \in \mathcal{B}(V)$. For $s \in \rho_{S}(T)$ we define the left $S$-resolvent operator as

$$
S_{L}^{-1}(s, T)=-\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}\right)^{-1}(T-\bar{s} \mathcal{I})
$$

and the right $S$-resolvent operator as

$$
S_{R}^{-1}(s, T)=-(T-\bar{s} \mathcal{I})\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}\right)^{-1}
$$

It is easy to show that the $S$-resolvent operators are slice hyperholomorphic operator-valued functions.

Theorem 2.7 ([5]). Let $T \in \mathcal{B}(V)$.
(i) The left $S$-resolvent operator $S_{L}^{-1}(s, T)$ is a $\mathcal{B}(V)$-valued right-slice hyperholomorphic function of the variable $s$ on $\rho_{S}(T)$.
(ii) The right $S$-resolvent operator $S_{R}^{-1}(s, T)$ is a $\mathcal{B}(V)$-valued left-slice hyperholomorphic function of the variable $s$ on $\rho_{S}(T)$.
Furthermore, they also give rise to a resolvent equation involving both resolvent operators. Hereby, one has to be careful that due to the noncommutativity the resolvent operators can be used only in a fixed order.

Theorem $2.8(3)$. Let $T \in \mathcal{B}(V)$, and let $s, p \in \rho_{S}(T)$. Then the equalities

$$
\begin{aligned}
S_{R}^{-1}(s, T) S_{L}^{-1}(p, T)= & {\left[\left(S_{R}^{-1}(s, T)-S_{L}^{-1}(p, T)\right) p-\bar{s}\left(S_{R}^{-1}(s, T)-S_{L}^{-1}(p, T)\right)\right] } \\
& \cdot\left(p^{2}-2 \operatorname{Re}(s) p+|s|^{2}\right)^{-1} \\
= & \left(s^{2}-2 \operatorname{Re}[p] s+|p|^{2}\right)^{-1} \\
& \cdot\left[\left(S_{L}^{-1}(p, T)-S_{R}^{-1}(s, T)\right) \bar{p}-s\left(S_{L}^{-1}(p, T)-S_{R}^{-1}(s, T)\right)\right]
\end{aligned}
$$

hold true.
As in the complex case, it is possible to define some splitting of the $S$-spectrum, and to this end we recall the following well-known theorem, whose proof is the same as in the complex case.

Theorem 2.9. A quaternionic linear operator $A$ that satisfies the two conditions
(i) there exists $K>0$ such that $\|A v\| \geq K\|v\|$ for $v \in D(A)$ ( $A$ is bounded from below), and
(ii) the range of $A$ is dense
is invertible.
The following definition for the splitting of the spectrum is based on the previous theorem on the invertibility of linear operators.
Definition 2.10. The point $S$-spectrum of $T$, denoted by $\Pi_{0, S}(T)$, is defined as

$$
\Pi_{0, S}(T)=\left\{s \in \mathbb{H}: T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I} \text { is not one-to-one }\right\}
$$

The approximate point $S$-spectrum of $T$, denoted by $\Pi_{S}(T)$, is defined as

$$
\Pi_{S}(T)=\left\{s \in \mathbb{H}: T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I} \text { is not bounded from below }\right\}
$$

The compression $S$-spectrum of $T$, denoted by $\Gamma_{S}(T)$, is defined as

$$
\Gamma_{S}(T)=\left\{s \in \mathbb{H}: \text { the range of } T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I} \text { is not dense }\right\}
$$

From the definition it follows that

$$
\Pi_{0, S}(T) \subset \Pi_{S}(T)
$$

There are several basic statements about the $S$-spectrum which are the analogues of the corresponding well-known facts in the classic case. While the main ideas to
prove the results below follow those of the complex case, the proofs contain some suitable substantial changes as they involve the pseudo-resolvent.

We start by proving a result generalizing the Fredholm alternative theorem.
Theorem 2.11. Let $T$ be a compact operator acting on a quaternionic Hilbert space $\mathcal{H}$, and let $s \neq 0$. If $\operatorname{ker}\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}\right)=\{0\}$, then $T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}$ is invertible.

Proof. We divide the proof in three steps.
Step 1. We set $A_{s}(T)=T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}$, and we prove that if $\operatorname{ran}\left(A_{s}(T)\right)=\mathcal{H}$ then $\operatorname{ker}\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}\right)=\{0\}$.

First of all we note that when $T$ is compact, $T^{2}-2 s_{0} T$ is also compact.
Then we define $\mathcal{Q}_{n, s}:=\operatorname{ker}\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}\right)^{n}, n=1,2, \ldots$, and, by absurdity, we assume that $\mathcal{Q}_{1, s} \neq\{0\}$ and $0 \neq v_{1} \in \mathcal{Q}_{1, s}$ : since $\operatorname{ran}\left(A_{s}(T)\right)=$ $\mathcal{H}$, we can find $v_{2}$ such that $A_{s}(T) v_{2}=v_{1}$ and that $A_{s}(T)^{2} v_{2}=A_{s}(T) v_{1}=0$, i.e., $v_{2} \in \mathcal{Q}_{2, s}$. Iterating the procedure, we can find $v_{n+1} \in \mathcal{Q}_{n+1, s}$ such that $A_{s}(T) v_{n+1}=v_{n}, n=1,2, \ldots$ In conclusion, $v_{n} \in \mathcal{Q}_{n, s}$ for all $n=1,2, \ldots$, and the smallest power that annihilates $v_{n}$ is the $n$th power. Thus $\mathcal{Q}_{n, s} \subset \mathcal{Q}_{n+1, s}$, and the sequence $\left\{\mathcal{Q}_{n, s}\right\}$ is strictly increasing. We can form a sequence $\epsilon_{1}, \epsilon_{2}, \ldots$ such that $\epsilon_{n} \in \mathcal{Q}_{n, s}(T)$ for all $n$, and the elements of the sequence are orthonormal. Since $A_{s}(T) \epsilon_{n+1} \in \mathcal{Q}_{n, s}, A_{s}(T) \epsilon_{n+1}$ is orthogonal to $\epsilon_{n+1}$, so

$$
\begin{aligned}
\left\|\left(T^{2}-2 s_{0} T\right) \epsilon_{n+1}\right\|^{2} & =\left\|A_{s}(T) \epsilon_{n+1}-|s|^{2} \epsilon_{n+1}\right\|^{2} \\
& =\left\|A_{s}(T) \epsilon_{n+1}\right\|^{2}+|s|^{2}\left\|\epsilon_{n+1}\right\|^{2} \geq|s|^{2} \neq 0
\end{aligned}
$$

Since $\epsilon_{n} \rightarrow 0$ weakly, this contradicts the fact that $T^{2}-2 s_{0} T$ is compact.
Step 2. We prove that $A_{s}(T)$ is bounded from below on $\operatorname{ker}\left(A_{s}(T)\right)^{\perp}$.
By absurdity, we assume that the assertion does not hold, so there exist unit vectors $\epsilon_{n} \in \operatorname{ker}\left(A_{s}(T)\right)^{\perp}$ such that $A_{s}(T) \epsilon_{n} \rightarrow 0$.

Since $T^{2}-2 s_{0} T$ is compact, we can assume, with no loss of generality, that the sequence $\left(T^{2}-2 s_{0} T\right) \epsilon_{n}$ is (strongly) convergent to an element $\epsilon$. Thus we have

$$
|s|^{2} \epsilon_{n}=A_{s}(T) \epsilon_{n}-\left(T^{2}-2 s_{0} T\right) \epsilon_{n} \rightarrow-\epsilon
$$

so $\epsilon \in \operatorname{ker}\left(A_{s}(T)\right)^{\perp}$ and it is a unit vector. However, $A_{s}(T) \epsilon_{n}=A_{s}(T) \epsilon$, so $A_{s}(T) \epsilon=0$. This fact yields $\epsilon \in \operatorname{ker}\left(A_{s}(T)\right)$, and hence $\epsilon=0$. This contradicts the fact that $\epsilon$ has norm 1, and the assertion follows.

Step 3. We show that Steps 1 and 2 apply when we consider $T^{*}, A_{s}(T)^{*}$ instead of $T, A_{s}(T)$.

We note that if Steps 1 and 2 hold, then since $\operatorname{ran}\left(A_{s}(T)\right)=A_{s}(T)\left(\operatorname{ker}\left(A_{s}(T)\right)^{\perp}\right)=$ $\mathcal{H}$ and $A_{s}(T)$ is bounded from below, $\operatorname{ran}\left(A_{s}(T)\right)$ is closed and $\operatorname{ran}\left(A_{s}(T)^{*}\right.$ is also closed. Assume that $\operatorname{ker}\left(A_{s}(T)\right)=\{0\}$. Then $\operatorname{ran}\left(A_{s}(T)\right)^{*}$ is dense in $\mathcal{H}$, and since it is closed, it follows that $\operatorname{ran}\left(A_{s}(T)^{*}\right)=\mathcal{H}$, so Step 1 applies to $\left(A_{s}(T)^{*}\right.$. We then conclude that $\operatorname{ker}\left(A_{s}(T)^{*}\right)=\{0\}$, and also that $\operatorname{ker}\left(A_{s}(T)^{*}\right)^{\perp}=\mathcal{H}$. Then Step 2 can be applied to $A_{s}(T)^{*}$, leading to the conclusion that $A_{s}(T)^{*}$ is bounded from below. Theorem 2.9 yields the result that $A_{s}(T)^{*}$ is invertible, so $A_{s}(T)$ is also invertible, and this concludes the proof.

Theorem 2.12. Let $T \in \mathcal{B}(\mathcal{H})$. Then $\sigma_{S}(T)=\Pi_{S}(T) \cup \Gamma_{S}(T)$.

Proof. We have to show that if $s \notin \Pi_{S}(T)$ and $s \notin \Gamma_{S}(T)$, then $s \notin \sigma_{S}(T)$. But $s \notin \Pi_{S}(T)$ implies that the range of $T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}$ is closed. Since $s \notin \Gamma_{S}(T)$, the range of $T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}$ is dense, so we have $T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}$ being one-to-one and onto; thus it is invertible.

Theorem 2.13 (Weyl's theorem). If $A \in \mathcal{B}(\mathcal{H})$ and $K$ is a compact operator, then

$$
\sigma_{S}(A+K) \subset \sigma_{S}(A) \cup \Pi_{0, S}(A+K)
$$

Proof. Assume that $s \in \sigma_{S}(A+K) \backslash \sigma_{S}(A)$. Then, since $A^{2}-2 s_{0} A+|s|^{2} \mathcal{I}$ is invertible by assumption and $A K+K A$ is compact since $K$ is compact, we have

$$
\begin{aligned}
& (A+K)^{2}-2 s_{0}(A+K)+|s|^{2} \mathcal{I}=A^{2}-2 s_{0} A+|s|^{2} \mathcal{I}+\left(K^{2}+A K+K A-2 s_{0} K\right) \\
& \quad=\left(A^{2}-2 s_{0} A+|s|^{2} \mathcal{I}\right)\left(\mathcal{I}+\left(A^{2}-2 s_{0} A+|s|^{2} \mathcal{I}\right)^{-1}\left(K^{2}+A K+K A-2 s_{0} K\right)\right)
\end{aligned}
$$

We conclude, by the invertibility of $A^{2}-2 s_{0} A+|s|^{2} \mathcal{I}$, that $\mathcal{I}+\left(A^{2}-2 s_{0} A+\right.$ $\left.|s|^{2} \mathcal{I}\right)^{-1}\left(K^{2}+A K+K A-2 s_{0} K\right)$ cannot be invertible. It follows from Theorem 2.11 that -1 is an eigenvalue of the compact operator $\left(A^{2}-2 s_{0} A+|s|^{2} \mathcal{I}\right)^{-1}\left(K^{2}+A K+\right.$ $\left.K A-2 s_{0} K\right)$. Hence, there exists a nonzero $v$ such that $\left(A^{2}-2 s_{0} A+|s|^{2} \mathcal{I}\right)^{-1}\left(K^{2}+\right.$ $\left.A K+K A-2 s_{0} K\right) v=-v$, which implies that

$$
\left(K^{2}+A K+K A-2 s_{0} K\right) v+\left(A^{2}-2 s_{0} A+|s|^{2} \mathcal{I}\right) v=0
$$

i.e.,

$$
\left((A+K)^{2}-2 s_{0}(A+K)+|s|^{2} \mathcal{I}\right) v=0
$$

Thus $\left((A+K)^{2}-2 s_{0}(A+K)+|s|^{2} \mathcal{I}\right)$ has a nontrivial null-space and $s \in \Pi_{0, S}(A+$ $K)$.

We also need a result on the boundary of the $S$-spectrum, which will be important for the study of invariant subspaces. Let $U$ be a subset in $\mathbb{H}$. We define the point-set boundary of $U$ as $\partial U=\bar{U} \cap(\overline{\mathbb{H} \backslash U})$.

Theorem 2.14. Let $T \in \mathcal{B}(\mathcal{H})$. Then we have $\partial \sigma_{S}(T) \subset \Pi_{S}(T)$.
Proof. First observe that $\partial \sigma_{S}(T)=\sigma_{S}(T) \cap \overline{\rho_{S}(T)}$. Now assume that $s \in \partial \sigma_{S}(T)$ and $s \notin \Pi_{S}(T)$. We can take a sequence $s_{n}$ in the set $\rho_{S}(T)$ such that $s_{n} \rightarrow s$.

Step 1. We show that there exists $K>0$ and a positive integer $N$ such that $n \geq N$ implies that

$$
\left\|\left(T^{2}-2 \operatorname{Re}\left(s_{n}\right) T+\left|s_{n}\right|^{2} \mathcal{I}\right) v\right\| \geq K\|v\| \quad \text { for all } v \in \mathcal{H}
$$

Suppose that this does not hold. Then for all positive integers $m$ and $N$ there would exists an $n \geq N$ and a vector $v_{m}$ with $\left\|v_{m}\right\|=1$ such that

$$
\left\|\left(T^{2}-2 \operatorname{Re}\left(s_{n}\right) T+\left|s_{n}\right|^{2} \mathcal{I}\right) v_{m}\right\| \leq 1 / m
$$

But observe that

$$
\begin{aligned}
& \left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}\right) v_{m} \\
& \quad=\left(T^{2}-2 \operatorname{Re}\left(s_{n}\right) T+\left|s_{n}\right|^{2} \mathcal{I}\right) v_{m}+2\left(\operatorname{Re}\left(s_{n}\right)-\operatorname{Re}(s)\right) T v_{m}+\left(|s|^{2}-\left|s_{n}\right|^{2}\right) v_{m}
\end{aligned}
$$

Taking the norm, we have
and this implies that $s \in \Pi_{S}(T)$. So such $K$ and $N$ do not exist.
Step 2. We can show now that $s \notin \Gamma_{S}(T)$, for if $v \in \mathcal{H}$, then for each $n$ there is a $w_{n}$ with

$$
\left(T^{2}-2 \operatorname{Re}\left(s_{n}\right) T+\left|s_{n}\right|^{2} \mathcal{I}\right) w_{n}=v
$$

but since

$$
\left\|\left(T^{2}-2 \operatorname{Re}\left(s_{n}\right) T+\left|s_{n}\right|^{2} \mathcal{I}\right) w_{n}\right\| \geq K\left\|w_{n}\right\|
$$

we have

$$
\left\|w_{n}\right\| \leq \frac{1}{K}\|v\| \quad \text { for } n \geq N
$$

Now observe that

If $n$ is large, the term $\left(2\left|\operatorname{Re}\left(s_{n}\right)-\operatorname{Re}(s)\right|\|T\|+\|\left. s\right|^{2}-\left|s_{n}\right|^{2} \mid\right) \frac{1}{K}\|v\|$ is arbitrarily small, and it follows that $s \notin \Gamma_{S}(T)$. Hence, $s \in \partial \sigma_{S}(T)$ and $s \notin \Gamma_{S}(T)$, which implies that $s \notin \sigma_{S}(T)$. But this contradicts Theorem 2.12.

The above theorem gives information about the spectra of the restrictions to invariant subspaces.

Definition 2.15. Let $T \in \mathcal{B}(\mathcal{H})$. The full $S$-spectrum of $T$, denoted by $\eta\left(\sigma_{S}(T)\right)$, is the union of $\sigma_{S}(T)$ and all bounded components of $\rho_{S}(T)$.

This means that $\eta\left(\sigma_{S}(T)\right)$ is the $S$-spectrum together with the holes in $\sigma_{S}(T)$. We now recall some basic facts useful to defining the $S$-functional calculus.
Definition 2.16 ( $T$-admissible slice domain). Let $T \in \mathcal{B}(\mathcal{H})$. A bounded axially symmetric domain $U \subset \mathbb{H}$ is called $T$-admissible if $\sigma_{S}(T) \subset U$ and $\partial\left(U \cap \mathbb{C}_{I}\right)$ is the union of a finite number of piecewise continuously differentiable Jordan curves for any $I \in \mathbb{S}$.
Definition 2.17. Let $T \in \mathcal{B}(\mathcal{H})$.
(i) A function $f$ is called locally left- (resp., right-) slice hyperholomorphic on $\sigma_{S}(T)$ if there exists a $T$-admissible slice domain $U \subset \mathbb{H}$ such that $f \in \mathcal{S H}_{L}(\bar{U})$ (resp., $\left.f \in \mathcal{S H}_{R}(\bar{U})\right)$. We denote the set of all locally left-
(resp., right-) slice hyperholomorphic functions on $\sigma_{S}(T)$ by $\mathcal{S H}_{L}\left(\sigma_{S}(T)\right)$ (resp., $\mathcal{S H}_{R}\left(\sigma_{S}(T)\right)$ ).
(ii) By $\mathcal{N}\left(\sigma_{S}(T)\right)$ we denote the set of all functions $f \in \mathcal{S} \mathcal{H}_{L}\left(\sigma_{S}(T)\right)$ such that there exists a $T$-admissible slice domain $U$ with $f\left(U \cap \mathbb{C}_{\mathbb{I}}\right) \subset \mathbb{C}_{\mathbb{I}}$ for all $I \in \mathbb{S}$.

Definition 2.18 ( $S$-functional calculus). Let $T \in \mathcal{B}(\mathcal{H})$. For any $f \in \mathcal{S} \mathcal{H}_{L}\left(\sigma_{S}(T)\right)$, we define

$$
\begin{equation*}
f(T)=\frac{1}{2 \pi} \int_{\partial\left(U \cap \mathbb{C}_{\mathbb{I}}\right)} S_{L}^{-1}(s, T) d s_{\mathbb{I}} f(s) \tag{2.2}
\end{equation*}
$$

where $\mathbb{I}$ is an arbitrary imaginary unit and $U$ is an arbitrary $T$-admissible slice domain such that $f$ is left-slice hyperholomorphic on $\bar{U}$. For any $f \in \mathcal{S H} \mathcal{H}_{R}\left(\sigma_{S}(T)\right)$, we define in a similar way

$$
\begin{equation*}
f(T)=\frac{1}{2 \pi} \int_{\partial\left(U \cap \mathbb{C}_{\mathbb{I}}\right)} f(s) d s_{\mathbb{I}} S_{R}^{-1}(s, T) \tag{2.3}
\end{equation*}
$$

For more details, and for the Banach space setting, see [3, 5, 16].

## 3. Quaternionic operators on a Hilbert space

Let $\mathcal{H}$ be a right Hilbert (separable) space over $\mathbb{H}$. Moreover, we assume that $\mathcal{B}(\mathcal{H})$ has identity $\mathcal{I}$. For the time being we often omit the identity operator from the formulations, its presence being clear from context. Let us first define the notion of an invariant subspace.

Definition 3.1. The subspace $\mathcal{M} \subset \mathcal{H}$ is invariant under the operator $T \in \mathcal{B}(\mathcal{H})$ if $T x \in \mathcal{M}$ for every $x \in \mathcal{M}$. The collection of all subspaces of $\mathcal{H}$ invariant under $T$ is denoted as $\operatorname{Lat}(T)$; if $\mathcal{B}^{\prime} \subset \mathcal{B}(\mathcal{H})$ then $\operatorname{Lat}\left(\mathcal{B}^{\prime}\right):=\cap_{T \in \mathcal{B}^{\prime}} \operatorname{Lat}(T)$.

Here, we have immediately the following property.
Theorem 3.2. Let $M \in \operatorname{Lat}(T)$. Then $\sigma_{S}\left(\left.T\right|_{M}\right) \subset \eta\left(\sigma_{S}(T)\right)$, where $\eta\left(\sigma_{S}(T)\right)$ is the full $S$-spectrum of $T$.

Proof. Observe that $s \in \Pi_{S}\left(\left.T\right|_{M}\right)$ implies that there exists a sequence $v_{n}$, with $\left\|v_{n}\right\|=1$, such that $\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}\right) v_{n}$ converges to 0 , so $\Pi_{S}\left(\left.T\right|_{M}\right) \subset \Pi_{S}(T)$. By Theorem 2.14 we also have

$$
\partial \sigma_{S}\left(\left.T\right|_{M}\right) \subset \Pi_{S}\left(\left.T\right|_{M}\right) \subset \sigma_{S}(T)
$$

If $\sigma_{S}\left(\left.T\right|_{M}\right)$ contained points of the unbounded component of $\rho_{S}(T)$, then $\partial \sigma_{S}\left(\left.T\right|_{M}\right)$ would have to meet the unbounded component of $\rho_{S}(T)$ too, and the above shows that this is impossible.

Additionally, we have the following notion of hyperinvariant subspaces.
Definition 3.3. The subspace $\mathcal{M}$ is hyperinvariant under the operator $T$ if $\mathcal{M} \in$ $\operatorname{Lat}(B)$ for every $B$ which commutes with $T$.

Hyperinvariant subspaces of $T$ give information about the commutants of $T$, that is, the set of all operators $B$ such that $[T, B]=T B-B T=0$.

For the $S$-spectrum we also need a statement about the spectral radius; see [16].

Definition 3.4. Let $T \in \mathcal{B}(\mathcal{H})$. Then the $S$-spectral radius of $T$ is defined to be the nonnegative real number

$$
r_{S}(T)=\sup \left\{|s|: s \in \sigma_{S}(T)\right\}
$$

Theorem 3.5. For $T \in \mathcal{B}(\mathcal{H})$, we have

$$
r_{S}(T)=\lim _{n \rightarrow \infty}\left\|T^{n}\right\|^{\frac{1}{n}}
$$

Observe that, for normal operators on a Hilbert space, the above theorem means that the spectral radius is given by

$$
r_{S}(T)=\|T\|
$$

since $\left\|T^{n}\right\|=\|T\|^{n}, n \in \mathbb{N}$, as in the complex case.
In the following we are in need of a spectral mapping theorem for the pseudoresolvent operator $Q_{S}(T)=\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2} \mathcal{I}\right)^{-1}$. Unfortunately, as we have already observed in the introduction, the function $s \mapsto\left(p^{2}-2 \operatorname{Re}(s) p+|s|^{2}\right)^{-1}$ defined for $p \notin[s]$ is neither left- nor right-slice hyperholomorphic, so we cannot use the $S$-functional calculus to prove the spectral mapping theorem in the case of a quaternionic Banach space. But since we are working in a Hilbert space and the operator $T$ is normal, we can use the continuous functional calculus for normal operators to deduce the spectral mapping theorem that we need.

In the sequel we also need to define a left multiplication in a right quaternionic Hilbert space. We assume that $\mathcal{H}$ is separable. This is always possible once a Hilbert basis $\left(e_{n}\right)_{n \in \mathbb{N}}$ has been fixed (see [25,42]), and it is defined by $s v=\sum_{n \in \mathbb{N}} e_{n} s\left\langle e_{n}, v\right\rangle$, where $v=\sum_{n \in \mathbb{N}} e_{n}\left\langle e_{n}, v\right\rangle$.
Theorem 3.6. Let $T \in \mathcal{B}(\mathcal{H})$ be normal, and let $\mathcal{H}$ be a quaternionic Hilbert space. Then there exist uniquely determined operators $A$ and $B$ which both belong to $\mathcal{B}(\mathcal{H})$, and an operator $J \in \mathcal{B}(\mathcal{H})$ which is uniquely determined on $\left\{\operatorname{Ker}\left(T-T^{*}\right)\right\}^{\perp}$ so that the following properties hold:

$$
T=A+J B
$$

where $A$ is self-adjoint, $B$ is positive, $J$ is anti-self-adjoint and unitary, and $A, B$, and $J$ mutually commute. Moreover, for any fixed $\mathbb{J} \in \mathbb{S}$, there exists an orthonormal basis $\mathcal{N}_{\mathbb{J}}$ of $\mathcal{H}$ with the property that $J=L_{\mathbb{J}}$, where $L_{\mathbb{J}}$ is the left multiplication operator by $\mathbb{J} \in \mathbb{S}$.

The decomposition $T=A+J B$, where $J$ is a partial isometry, was first established by Teichmüller [43]. The continuous functional calculus for normal operators on a quaternionic Hilbert space is defined for the following class of continuous quaternionic-valued functions.

Definition 3.7. Let $\Omega \subseteq \mathbb{H}$ be an axially symmetric set, and let $D \subseteq \mathbb{R}^{2}$ be such that

$$
D=\left\{(u, v) \in \mathbb{R}^{2}: u+\mathbb{J} v \in \Omega \text { for some } \mathbb{J} \in \mathbb{S}\right\}
$$

Let $\mathcal{S}(\Omega, \mathbb{H})$ denote the quaternionic linear space of slice continuous functions, i.e., $\mathcal{S}(\Omega, \mathbb{H})$ consists of functions $f: \Omega \rightarrow \mathbb{H}$ of the form

$$
f(u+\mathbb{J} v)=f_{0}(u, v)+\mathbb{J} f_{1}(u, v) \quad \text { for }(u, v) \in D \quad \text { and for } \mathbb{J} \in \mathbb{S}
$$

where $f_{0}$ and $f_{1}$ are continuous $\mathbb{H}$-valued functions on $D$ such that

$$
f_{0}(u, v)=f_{0}(u,-v)
$$

and

$$
f_{1}(u, v)=-f_{1}(u,-v)
$$

If $f_{0}$ and $f_{1}$ are real valued, then we say that the continuous slice function $f$ is intrinsic. The subspace of intrinsic continuous slice functions is denoted by $\mathcal{S}_{\mathbb{R}}(\Omega, \mathbb{H})$.

The following functional calculus will be useful for proving a spectral theorem for a normal operator $T \in \mathcal{B}(\mathcal{H})$.
Theorem 3.8 ([25], Theorem 7.4]). Let $T \in \mathcal{B}(\mathcal{H})$ be a normal operator. There exists a unique continuous *-homomorphism

$$
\Psi_{\mathbb{R}, T}: f \in \mathcal{S}_{\mathbb{R}}\left(\sigma_{S}(T), \mathbb{H}\right) \mapsto f(T) \in \mathcal{B}(\mathcal{H})
$$

of real-Banach unital $C^{*}$-algebras such that (spectral mapping theorem)

$$
\begin{equation*}
\sigma_{S}(f(T))=f\left(\sigma_{S}(T)\right) \tag{3.1}
\end{equation*}
$$

We are now in a position to prove an important estimate on the pseudo-resolvent operator that will be used in the sequel to prove one of the main results of this paper.
Lemma 3.9. Let $T$ be a bounded normal linear operator on a quaternionic Hilbert space $\mathcal{H}$, and let $s \in \mathbb{H}$. Then we have

$$
\left\|\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2}\right)^{-1}\right\| \leq \frac{1}{\operatorname{dist}\left(\sigma_{S}(T),[s]\right)^{2}}
$$

where we have set

$$
\operatorname{dist}\left(\sigma_{S}(T),[s]\right):=\inf \left\{|w-p|, w \in \sigma_{S}(T), p \in[s]\right\}
$$

Proof. Since $T$ is a normal operator, $\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2}\right)^{-1}$ is also a normal operator, so the $S$-spectral radius gives

$$
\left\|\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2}\right)^{-1}\right\|=\sup \left\{|w|: w \in \sigma_{S}\left(\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2}\right)^{-1}\right)\right\}
$$

From the spectral mapping theorem (Theorem 3.8) we obtain

$$
\sup \left\{|w|: w \in \sigma_{S}\left(\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2}\right)^{-1}\right)\right\}=\frac{1}{\inf \left\{|w|: w \in \sigma_{S}\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2}\right)\right\}}
$$

and again using Theorem 3.8, we get

$$
\frac{1}{\left\{\inf |w|: w \in \sigma_{S}\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2}\right)\right.}=\frac{1}{\inf \left\{\left|w^{2}-2 \operatorname{Re}(s) w+|s|^{2}\right|: w \in \sigma_{S}(T)\right\}}
$$

From the above equalities we obtain

$$
\left\|\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2}\right)^{-1}\right\|=\frac{1}{\inf \left\{\left|w^{2}-2 \operatorname{Re}(s) w+|s|^{2}\right|: w \in \sigma_{S}(T)\right\}}
$$

Furthermore, we have

$$
\begin{aligned}
& \inf \left\{\left|w^{2}-2 \operatorname{Re}(s) w+|s|^{2}\right|: w \in \sigma_{S}(T)\right\}=\inf \left\{|(w-p) *(w-\bar{p})|: w \in \sigma_{S}(T), p \in[s]\right\} \\
& \quad= \inf \left\{|(w-p)(\tilde{w}-\bar{p})|: w \in \sigma_{S}(T), \tilde{w} \in[w], p \in[s]\right\} \\
& \geq \inf \left\{|w-p|: w \in \sigma_{S}(T), \tilde{w} \in[w], p \in[s]\right\} \\
& \times \inf \left\{|\tilde{w}-\bar{p}|: w \in \sigma_{S}(T), \tilde{w} \in[w], p \in[s]\right\} \\
&= \operatorname{dist}\left(\sigma_{S}(T),[s]\right)^{2}
\end{aligned}
$$

which leads to the statement.
4. Some results on the Schatten class of quaternionic operators

Since we shall discuss compact perturbations of normal operators, let us recall some basic statements on Schatten classes of quaternionic operators. These classes have been recently introduced in the paper [13].

We denote by $\mathcal{B}_{0}(\mathcal{H})$ the set of all compact quaternionic right linear operators on $\mathcal{H}$. For an anti-self-adjoint unitary operator $J$, we define the set

$$
\mathcal{B}_{J}(\mathcal{H}):=\{T \in \mathcal{B}(\mathcal{H}):[T, J]=0\} .
$$

Consider now an arbitrary compact operator $T$. We can find a Hilbert basis $\left(e_{n}\right)_{n \in \mathbb{N}}$ and an orthonormal set $\left(\sigma_{n}\right)_{n \in \mathbb{N}}$ in $\mathcal{H}$ such that

$$
\begin{equation*}
T x=\sum_{n \in \mathbb{N}} \sigma_{n} \lambda_{n}\left\langle e_{n}, x\right\rangle \quad \forall x \in \mathcal{H} \tag{4.1}
\end{equation*}
$$

where the $\lambda_{n} \in \mathbb{R}^{+}$are the singular values of $T$, i.e., the eigenvalues of the operator $|T|:=\sqrt{T^{*} T}$ in nonincreasing order, and where the vectors $\left(e_{n}\right)_{n \in \mathbb{N}}$ form an eigenbasis of $|T|$ and $\sigma_{n}=W e_{n}$, with $W$ unitary on ker $W^{\perp}$, and such that $T=W|T|$. See [19, [13, Remark 3.4].
Definition 4.1. Let $J \in \mathcal{B}(\mathcal{H})$ be an anti-self-adjoint and unitary operator. For $p \in(0,+\infty]$, we define the $(J, p)$-Schatten class of operators $S_{p}(J)$ as

$$
S_{p}(J):=\left\{T \in \mathcal{B}_{0}(\mathcal{H}):[T, J]=0 \text { and }\left(\lambda_{n}(T)\right)_{n \in \mathbb{N}} \in \ell^{p}\right\}
$$

where $\left(\lambda_{n}(T)\right)_{n \in \mathbb{N}}$ denotes the sequence of singular values of $T$, and $\ell^{p}$ and $\ell^{\infty}$ denote the space of $p$-summable and bounded sequences, respectively. For $T \in$ $S_{p}(J)$ we introduce the following norms:

$$
\begin{equation*}
\|T\|_{p}=\left(\sum_{n \in \mathbb{N}}\left|\lambda_{n}(T)\right|^{p}\right)^{\frac{1}{p}}, \quad p \in[1,+\infty), \quad\|T\|_{\infty}=\sup _{n \in \mathbb{N}} \lambda_{n}(T)=\|T\| \tag{4.2}
\end{equation*}
$$

Using these norms, we can give the following statements, whose proofs are straightforward modifications of the classic proofs.

Lemma 4.2. Let $T \in S_{p}(J)$. Then there exists a sequence of finite rank operators $\left\{T_{n}\right\}_{n \in \mathbb{N}}$ such that

$$
\left\|T-T_{n}\right\| \rightarrow 0 \quad \text { and } \quad\left\|T-T_{n}\right\|_{p} \rightarrow 0 \quad \text { as } n \rightarrow \infty
$$

Proof. The proof follows as in the classical case; see [19, Lemma 11, p. 1095].
Lemma 4.3. Let $T \in S_{p}(J)$. Then for every operator $A \in \mathcal{B}(\mathcal{H})$ the operators $A T$ and $T A$ belong to $S_{p}(J)$ and

$$
\|A T\|_{p} \leq\|A\|\|T\|_{p}
$$

and

$$
\|T A\|_{p} \leq\|A\|\|T\|_{p}
$$

Proof. From [13, Lemma 3.7] it has been established that if $T$ is a positive compact operator, the singular values $\lambda_{n+1}$ are given by

$$
\lambda_{n+1}=\min _{y_{1}, \ldots, y_{n}} \max _{\left\langle x_{i}, y_{i}\right\rangle, i=1, \ldots, n} \frac{\|T x\|}{\|x\|}
$$

so using this formula, we can define singular values also for operators which are not compact. Furthermore, with a similar proof to the complex case we can state that
for compact or noncompact bounded operators, we can extend [13, Corollary 3.9]. More precisely we have

$$
\begin{align*}
\lambda_{n+m+1}\left(T_{1}+T_{2}\right) & \leq \lambda_{n+1}\left(T_{1}\right)+\lambda_{m+1}\left(T_{2}\right), \\
\lambda_{n+m+1}\left(T_{1} T_{2}\right) & \leq \lambda_{n+1}\left(T_{1}\right) \lambda_{m+1}\left(T_{2}\right) . \tag{4.3}
\end{align*}
$$

As a particular case, we have

$$
\lambda_{n}(T A) \leq \lambda_{n}(T)\|A\|_{p}, \quad \lambda_{n}(A T) \leq \lambda(T)\|A\|_{p} \lambda(T)
$$

so we get the statement.
For the following definition we have to stress the fact that the Schatten classes under consideration are restricted to $k \in \mathbb{N}$.

Definition 4.4. Let $\mathbb{I} \in \mathbb{S}$ be any arbitrary, but fixed, element in $\mathbb{S}$. Let $T \in S_{k}(J)$ with $k \in \mathbb{N}$, and let $\left\{s_{1}, s_{2}, \ldots\right\}$ be an enumeration of the nonzero elements in $\Pi_{0, S}(T) \cap \mathbb{C}_{\mathbb{I}}$ repeated according to their multiplicity. We define

$$
\delta_{k, \mathbb{I}}(T)=\Pi_{l=1}^{\infty}\left[\left(1+s_{l}\right) \exp \left(-s_{l}+\frac{s_{l}^{2}}{2}+\cdots+(-1)^{k-1} \frac{s_{l}^{k-1}}{k-1}\right)\right]
$$

In the case in which $\Pi_{0, S}(T) \cap \mathbb{C}_{\mathbb{I}}=\{0\}$ we define $\delta_{k, \mathbb{I}}=1$.
For this function we have the following result.
Lemma 4.5. Let $T \in S_{k}(J)$ with $k \in \mathbb{N}$. Then
(i) $\delta_{k, \mathbb{I}}(T)$ is an absolutely convergent infinite product,
(ii) there exists a constant $\Gamma_{k}$ depending only on $k \in \mathbb{N}$ such that

$$
\left|\delta_{k, \mathbb{I}}(T)\right| \leq \exp \left(\Gamma_{k}\|T\|_{k}^{k}\right)
$$

(iii) $\delta_{k, \mathbb{I}}(T)$ is a continuous function in the topology of $S_{k}(J)$, and
(iv) there exists a constant $M_{k}$ depending only on $k \in \mathbb{N}$ such that

$$
\left\|\delta_{k, \mathbb{I}}(T)(\mathcal{I}+T)^{-1}\right\| \leq \exp \left(M_{k}\|T\|_{k}^{k}\right) \quad \text { when }-1 \notin \sigma_{S}(T)
$$

Proof. Since the function $\delta_{k, \mathbb{I}}(T)$ has values in $\mathbb{C}_{\mathbb{I}}$, the proof of (i) is the same proof as given for [19, Lemma 22(a), p. 1106]. Point (ii) is [19, Lemma 22(b), p. 1106] since we consider restrictions to the complex plane $\mathbb{C}_{\mathbb{I}}$ point (iii) to be [19, Lemma 22(c), p. 1106]. Finally, point (iv) is [19, Theorem 24, p. 1112].

Remark, moreover, that $\delta_{k, \mathbb{I}}$ does not depend on the chosen element $\mathbb{I} \in \mathbb{S}$.

## 5. Perturbation of quaternionic normal operators

Take $\mathbb{I} \in \mathbb{S}$ and consider the slice $\mathbb{C}_{\mathbb{I}}$. Let $\mathcal{C}$ be an exposed arc in $\sigma_{S}(T) \cap \mathbb{C}_{\mathbb{I}}$ for all $\mathbb{I} \in \mathbb{S}$, that is to say, there exists an open disk $\mathbb{D}_{\mathbb{I}}$ such that $\mathbb{D}_{\mathbb{I}} \cap \sigma_{S}(T)=\mathcal{C}$ and $\mathcal{C}$ is a smooth Jordan arc in $\mathbb{C}_{\mathbb{I}}, \mathbb{I} \in \mathbb{S}$. Furthermore, for a curve $C$ we will denote by $\tilde{C}$ its axially symmetric completion.

Definition 5.1. The distance between equivalence classes $[s],[t]$ is defined as

$$
|[s]-[t]|=\inf _{s \in[s], t \in[t]}|s-t| .
$$

Theorem 5.2. Let $T \in \mathcal{B}(\mathcal{H})$ be such that $\sigma_{S}(T)$ contains the axially symmetric completion $\tilde{\mathcal{C}}$ of an exposed $\operatorname{arc} \mathcal{C}$, and let $k \in \mathbb{N}$. If for each $\left[s_{0}\right] \in \tilde{\mathcal{C}}$ and each axially symmetric completion $\tilde{L}$ of a closed line segment $L$ not tangent to $\mathcal{C}$ and satisfying $\tilde{L} \cap \sigma_{S}(T)=\left\{\left[s_{0}\right]\right\}$, there exists a constant $K>0$ such that if

$$
\left\|S_{L}^{-1}(s, T)\right\| \leq \exp \left(K\left|[s]-\left[s_{0}\right]\right|^{-k}\right)
$$

for all $s \in \tilde{L} \backslash\left\{\left[s_{0}\right]\right\}$, then $T$ has a nontrivial hyperinvariant subspace.
Proof. Let $\mathbb{I} \in \mathbb{S}$ be arbitrary but fixed. We can assume that $\mathcal{C}_{\mathbb{I}}=\tilde{\mathcal{C}} \cap \mathbb{C}_{\mathbb{I}}$ has a representation (as a smooth Jordan arc in a given slice) $s=q(t), t \in(0,1)$, with $q$ one-to-one, $\left|q^{\prime}(t)\right|<\tan (\pi / 5 k), t \in(0,1)$, and where $q^{\prime \prime}(t)$ exists everywhere in $(0,1)$.

If $\mathbb{D}_{\mathbb{I}}$ is an open disk in $\mathbb{C}_{\mathbb{I}}$ such that $\mathbb{D}_{\mathbb{I}} \cap \sigma_{S}(T)=\mathcal{C}$ and that $\mathcal{C}$ is a smooth Jordan arc, then $\mathbb{D}_{\mathbb{I}}$ is the union of disjoint Jordan regions $\mathbb{D}_{1, \mathbb{I}}, \mathbb{D}_{2, \mathbb{I}}$ lying above and below $\mathcal{C}$, respectively.

Consider subarcs $\mathcal{J}$ such that $\overline{\mathcal{J}} \subset \tilde{\mathcal{C}} \cap \mathbb{C}_{\mathbb{I}}$, and with endpoints $s_{1}$ and $s_{2}$ (with $\operatorname{Re} s_{1}<\operatorname{Re} s_{2}$.) Construct a simple closed Jordan polygon $\Gamma_{1}(\mathcal{J}) \in \mathbb{D}_{\mathbb{I}}$ enclosing $\mathcal{J}$ and intersecting $\mathcal{C}$ at $s_{1}$ and $s_{2}$ only. Assume in the construction of $\Gamma_{1}(\mathcal{J}) \in \mathbb{D}_{\mathbb{I}}$ that the angles at $s_{1}$ have arguments $\pm \pi / 5 k$, while the angles at $s_{2}$ have arguments $\pi \pm$ $\pi / 5 k$. Then these lines generate a hexagon lying in $\mathbb{D}_{\mathbb{I}}$. Moreover, by interchanging the angles at $s_{1}$ and $s_{2}$ one obtains a second polygon $\Gamma_{1}^{\prime}(\mathcal{J}) \in \mathbb{D}_{\mathbb{I}}$. Let $\Gamma_{2}(\mathcal{J}) \in \mathbb{D}_{\mathbb{I}}$ be the union of $\Gamma_{1}^{\prime}(\mathcal{J})$ and any fixed circle containing $\mathbb{D}_{\mathbb{I}} \cap \sigma_{S}(T)$ in its interior.

Fix an open subarc $\mathcal{J}_{0}$ of $\mathcal{C}$ such that $\overline{\mathcal{J}}_{0} \subset \mathcal{C}$. Let $S_{L}^{-1}(s, T)$ denote the slice hyperholomorphic quaternionic-valued function taking the resolvent set $\rho_{S}(T)$ into $\mathcal{H}$.

We recall that, due to the noncommutativity of the quaternions, when we consider the $S$-resolvent operator $S_{L}^{-1}(s, T)$, which is right-slice hyperholomorphic, the function $S_{L}^{-1}(s, T) x$ cannot be right-slice hyperholomorphic. To avoid this problem, we consider the subset $\mathcal{H}_{\mathbb{R}}$ of $\mathcal{H}$ defined as

$$
\mathcal{H}_{\mathbb{R}}:=\{x \in \mathcal{H}: x p=p x \quad \forall p \in \mathbb{H}\}
$$

where we are using both the left and right multiplication in $\mathcal{H}$, and thus we have fixed a Hilbert basis.

Note that $\mathcal{H}=\sum_{i=0}^{3} \mathcal{H}_{\mathbb{R}} e_{i}$, where we set $e_{0}=1$. In fact, given any $x \in \mathcal{H}$, we can define the element $\operatorname{Re}(x)=\frac{1}{4}\left(\sum_{i=0}^{3} \bar{e}_{i} x e_{i}\right) \in \mathcal{H}_{\mathbb{R}}$, and we have $x=\sum_{i=0}^{3} \operatorname{Re}\left(\bar{e}_{i} x\right) e_{i}$. If two right linear operators $T$ and $\tilde{T}$ agree on $\mathcal{H}_{\mathbb{R}}$, then they agree on the entire $\mathcal{H}$; see [5] p. 176].

Let us define the sets
$\mathscr{N}_{R, \mathbb{R}}=\left\{x \in \mathcal{H}_{\mathbb{R}}: S_{R}^{-1}(s, T) x\right.$ has a left-slice hyperholomorphic extension to $\left.\left(\overline{\mathcal{J}}_{0}\right)^{c}\right\}$,

$$
\begin{align*}
\mathscr{N}_{L, \mathbb{R}}= & \left\{x \in \mathcal{H}_{\mathbb{R}}: S_{L}^{-1}(s, T) x\right. \text { has a right-slice hyperholomorphic extension to }  \tag{5.2}\\
& \left.\left(\overline{\mathcal{J}}_{0}\right)^{c}\right\}
\end{align*}
$$

where $\left(\overline{\mathcal{J}}_{0}\right)^{c}$ denotes the complement set of $\overline{\mathcal{J}}_{0}$. Then $\mathscr{N}_{L, \mathbb{R}}=\mathscr{N}_{R, \mathbb{R}}$. Indeed, we have for $x \in \mathscr{N}_{L, \mathbb{R}}$ that there exists a slice hyperholomorphic continuation

$$
f(s)=S_{L}^{-1}(s, T) x
$$

to $\left(\overline{\mathcal{J}}_{0}\right)^{c}$. In a similar way, for $x \in \mathscr{N}_{R, \mathbb{R}}$ there exists a slice hyperholomorphic continuation to $\left(\overline{\mathcal{J}}_{0}\right)^{c}$,

$$
\tilde{f}(s)=S_{R}^{-1}(s, T) x
$$

Let us prove that $\mathscr{N}_{L, \mathbb{R}} \subseteq \mathscr{N}_{R, \mathbb{R}}:$ consider $x \in \mathscr{N}_{L, \mathbb{R}}$. Then

$$
x=(s-T) \star_{r} S_{L}^{-1}(s, T) x=(s-T) \star_{r} f(s)
$$

so

$$
S_{R}^{-1}(s, T) x=S_{R}^{-1}(s, T)(s-T) \star_{r} f(s):=\tilde{f}(s)
$$

is a slice hyperholomorphic continuation and $x \in \mathscr{N}_{R, \mathbb{R}}$. In a similar way, $\mathscr{N}_{R, \mathbb{R}} \subseteq$ $\mathscr{N}_{L, \mathbb{R}}$; note that these sets are real subspaces of $\mathcal{H}$.

In order to construct a subspace of $\mathcal{H}$ as a quaternionic linear space, we recall that each $x \in \mathcal{H}$ can be uniquely decomposed as $x=\sum_{i=0}^{3} x_{i} e_{i}$, and if we set

$$
\mathscr{N}_{R}=\sum_{i=0}^{3} \mathscr{N}_{R, \mathbb{R}} e_{i}, \quad \mathscr{N}_{L}=\sum_{i=0}^{3} \mathscr{N}_{L, \mathbb{R}} e_{i}
$$

and $e_{0}=1$, we deduce from the previous discussion that $\mathscr{N}_{R}=\mathscr{N}_{L}$. From now on, we will denote these sets as $\mathscr{N}$.

We point out that in the case of $\mathscr{N}_{R}$ one could have introduced it directly:

$$
\begin{equation*}
\mathscr{N}_{R}=\left\{x \in \mathcal{H}: S_{R}^{-1}(s, T) x \text { has a left-slice hyperholomorphic extension to }\left(\overline{\mathcal{J}}_{0}\right)^{c}\right\} \tag{5.3}
\end{equation*}
$$

since there are no issues of loosing the left hyperholomorphy of $S_{R}^{-1}(s, T)$ by letting it act on $x \in \mathcal{H}$; however, to show the equality $\mathscr{N}_{R}=\mathscr{N}_{L}$, it is more convenient to proceed as above. We now note that it is not immediate to prove the hyperinvariance of $\mathscr{N}$; in fact, in general, $A$ does not commute with the operator $\bar{s} \mathcal{I}$. Thus we consider

$$
\begin{equation*}
\mathscr{M}=\left\{x \in \mathcal{H}: Q_{s}(T) x \in \mathcal{H} \text { for all } s \in\left(\overline{\mathcal{J}}_{0}\right)^{c}\right\} \tag{5.4}
\end{equation*}
$$

Obviously, as $A T=T A$, one gets

$$
\left(T^{2}-2 s \operatorname{Re}(s) T+|s|^{2}\right)^{-1}(A x)=A\left(T^{2}-2 \operatorname{Re}(s) T+|s|^{2}\right)^{-1} x
$$

Hence, $\mathscr{M}$ is invariant under every operator $A$ which commutes with $T$. We now show that $\mathscr{N}=\mathscr{M}$. Every $x \in \mathscr{M}$ is such that $Q_{s}(T) x \in \mathcal{H}$ for all $s \in\left(\overline{\mathcal{J}}_{0}\right)^{c}$; thus

$$
-(T-\bar{s}) Q_{s}(T) x=S_{R}^{-1}(s, T) x \in \mathcal{H} \quad \text { for all } s \in\left(\overline{\mathcal{J}}_{0}\right)^{c}
$$

so $x \in \mathscr{N}$.
Conversely, consider $x \in \mathscr{N}=\mathscr{N}_{R}$. Then $-(T-\bar{s}) Q_{s}(T) x$ admits left-slice hyperholomorphic extension to $\left(\overline{\mathcal{J}}_{0}\right)^{c}$, so $-(T-\bar{s}) Q_{s}(T) x \in \mathcal{H}$ and $Q_{s}(T) x$ belongs to the domain of $T$, which is $\mathcal{H}$ and thus $Q_{s}(T) x \in \mathcal{H}$ for $s \in\left(\overline{\mathcal{J}}_{0}\right)^{c}$. Thus $\mathscr{N}=\mathscr{M}$ and the hyperinvariance of $\mathscr{N}$ is proved.

We define the functions $m_{r}, m_{l}$ as

$$
m(s):=\left\{\begin{array}{cl}
\exp _{\star}\left[-\left(s-s_{1}\right)^{\star(-2 k)}-\left(s-s_{2}\right)^{\star(-2 k)}\right], & s \neq s_{1}, s_{2}  \tag{5.5}\\
0, & s=s_{1}, s_{2}
\end{array}\right.
$$

with

$$
\exp _{\star}\left[-\left(s-s_{1}\right)^{\star(-2 k)}-\left(s-s_{2}\right)^{\star(-2 k)}\right]:=\sum_{n=0}^{\infty} \frac{1}{n!}\left[-\left(s-s_{1}\right)^{\star(-2 k)}-\left(s-s_{2}\right)^{\star(-2 k)}\right]^{\star n}
$$

where $m_{r}$ and $m_{l}$ correspond to the appropriate $\star_{r}$ or $\star_{l}$ multiplication.

Let $G$ be an open annuluslike region whose boundary is $\Gamma_{2}(\mathcal{J})$. After a judicious choice for $\Gamma_{1}(\mathcal{J})$ at $s_{1}, s_{2}$ it follows that both $m_{r}$ and $m_{l}$ are slice hyperholomorphic on $\tilde{G}$ and continuous on $\tilde{G}$. Take now a sequence $\left(x_{n}\right)_{n \in \mathbb{N}}$ in $\mathscr{N}$ such that $x_{n} \rightarrow x \in$ $\mathcal{H}$. Moreover, denote by $S_{L, n}^{-1}(s, T)\left(x_{n}\right)$ the slice hyperholomorphic continuation of $S_{L}^{-1}(s, T)\left(x_{n}\right)$ to the complement of $\overline{\mathcal{J}}_{0}$. Then

$$
\begin{aligned}
& \left\|S_{L, n}^{-1}(s, T) \star_{r} m_{r}(s)-S_{L, k}^{-1}(s, T) \star_{r} m_{r}(s)\right\| \\
& \quad \leq \sup _{w \in \Gamma_{2}(\mathcal{J})}\left\|\left(S_{L, n}^{-1}(w, T)-S_{L, k}^{-1}(w, T)\right) \star_{r} m_{r}(w)\right\|
\end{aligned}
$$

by the maximum modulus principle. By the hypothesis on the growth of the pseudoresolvent of $T$, given a line $L \subset \Gamma_{2}(\mathcal{J})$ with an endpoint on $s_{1}$, we have, for $w \in L \backslash\left\{s_{1}\right\}$,

$$
\begin{aligned}
& \left\|\left(S_{L, n}^{-1}(w, T)-S_{L, k}^{-1}(w, T)\right) \star_{r} m_{r}(w)\right\| \\
& \quad=\left\|\left(S_{L}^{-1}(w, T)-S_{L}^{-1}(w, T)\right) \star_{r} m_{r}(w)\left(x_{n}-x_{k}\right)\right\| \\
& \quad \leq\left\|x_{n}-x_{k}\right\|\left\|\exp _{\star_{r}}\left[-\left(w-s_{1}\right)^{\star_{r}(-2 k)}-\left(w-s_{2}\right)^{\star_{r}(-2 k)}\right]\right\| \exp \left(K\left|w-s_{1}\right|^{-k}\right) \\
& \quad \leq N\left\|x_{n}-x_{k}\right\| \exp _{\star_{r}}\left[\operatorname{Sc}\left(-\left(w-s_{1}\right)^{\star_{r}(-2 k)}\right)\right] \exp \left(K\left|w-s_{1}\right|^{-k}\right)
\end{aligned}
$$

where

$$
N:=\sup _{w \in L}\left|\exp _{\star_{r}}\left[-\left(w-s_{2}\right)^{\star_{r}(-2 k)}\right]\right| .
$$

As $w, s_{1} \in L$, we have $w-s_{1}=\left|w-s_{1}\right| e^{I \theta}$ in the slice $\mathbb{C}_{\mathbb{I}}$ for a certain angle $\theta$ (either $\pi / 5 k$ or $-\pi / 5 k$ ). Then the term

$$
\exp _{\star_{r}}\left[\operatorname{Sc}\left(-\left(w-s_{1}\right)^{\star_{r}(-2 k)}\right)\right] \exp \left(K\left|w-s_{1}\right|^{-k}\right)
$$

is bounded on $L$, and there exists an $M_{1}>0$ such that

$$
\left\|S_{L, n}^{-1}(s, T) \star_{r} m_{r}(s)-S_{L, k}^{-1}(s, T) \star_{r} m_{r}(s)\right\| \leq M_{1}\left\|x_{n}-x_{k}\right\| \quad \text { for all } w \in L
$$

In exactly the same manner, it can be shown that there exists a constant $M_{2}>0$ such that

$$
\left\|S_{L, n}^{-1}(s, T) \star_{r} m_{r}(s)-S_{L, k}^{-1}(s, T) \star_{r} m_{r}(s)\right\| \leq M_{2}\left\|x_{n}-x_{k}\right\|
$$

holds for all $w$ on the lines of $\Gamma_{2}(\mathcal{J})$ passing trough $s_{2}$.
Since a similar statement holds for $w$ on the remaining lines of $\Gamma_{2}(\mathcal{J})$, we obtain that $\left(S_{L, n}^{-1}(s, T) \star_{r} m_{r}(s)\right)_{n \in \mathbb{N}}$ is a uniform Cauchy sequence on $\overline{\tilde{G}}$, and it converges uniformly to a function $g(s)$ right-slice hyperholomorphic on $\tilde{G}$ and continuous on $\overline{\tilde{G}}$. Let us consider $x \in \mathcal{H}_{\mathbb{R}}$, and let us set

$$
y=\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} S_{L}^{-1}(z, T) \star_{r} m(z) d z_{\mathbb{I}} x
$$

Take an arbitrary $w \in \rho_{S}(T)$ outside $\Gamma_{1}\left(\mathcal{J}_{0}\right)$. We get, with all of the $\star_{r}$-multiplications computed in the variable $z$,

$$
\begin{aligned}
& S_{R}^{-1}(w, T) y= \int_{\partial\left(\Gamma_{1}\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} S_{R}^{-1}(w, T) S_{L}^{-1}(z, T) \star_{r} m_{r}(z) d z_{\mathbb{I}} x \\
&= \int_{\partial\left(\Gamma_{1}\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)}(z-w)^{-\star_{r}} \star_{r}\left[S_{L}^{-1}(z, T)-S_{R}^{-1}(w, T)\right] \star_{r} m_{r}(z) d z_{\mathbb{I}} x \\
&= \int_{\partial\left(\Gamma_{1}\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)}(z-w)^{-\star_{r}} \star_{r} S_{L}^{-1}(z, T) \star_{r} m_{r}(z) d z_{\mathbb{I}} x \\
& \quad-\underbrace{\int_{\partial\left(\Gamma_{1}\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)}(z-w)^{-\star_{r}} \star_{r} S_{R}^{-1}(w, T) \star_{r} m_{r}(z) d z_{\mathbb{I}} x}_{=0} \\
&= \int_{\partial\left(\Gamma_{1}\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)}(z-w)^{-\star_{r}} \star_{r} S_{L}^{-1}(z, T) \star_{r} m_{r}(z) d z_{\mathbb{I}} x .
\end{aligned}
$$

Now the integrand has a slice hyperholomorphic continuation to the exterior of the curve $\Gamma_{1}\left(\mathcal{J}_{0}\right)$ such that it has a slice hyperholomorphic continuation to the complement of $\overline{\mathcal{J}_{0}}$, and such that $y \in \mathscr{N}_{R, \mathbb{R}}$.

Now let $x \in \mathcal{H}_{\mathbb{R}}$ so that, recalling that $\mathscr{N}_{R, \mathbb{R}}=\mathscr{N}_{L, \mathbb{R}}$, we have

$$
y=\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} S_{L}^{-1}(s, T) \star_{r} m_{r}(s) x d s_{\mathbb{I}}
$$

corresponding one-to-one to

$$
\tilde{y}=\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} d s_{\mathbb{I}} m_{l}(s) \star_{r} S_{R}^{-1}(s, T) x,
$$

that is to say, $y=0$ if and only if $\tilde{y}=0$.
Now let $s_{0} \in \mathcal{J}_{0}$. Thus $s_{0} \in \Pi_{S}(T)$, so for all $\epsilon>0$ there exists a unit vector $x_{\epsilon} \in \mathcal{H}_{\mathbb{R}}$ such that

$$
\left(T^{2}-2 \operatorname{Re}\left(s_{0}\right) T+\left|s_{0}\right|^{2} \mathcal{I}\right) x_{\epsilon}=-\left(T-\bar{s}_{0}\right) h_{\epsilon}
$$

with $\left\|h_{\epsilon}\right\|<\epsilon$. Hence,

$$
\begin{aligned}
\tilde{y} & =\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} d s_{\mathbb{I}} m_{l}(s) \star_{l} S_{R}^{-1}(s, T) x_{\epsilon} \\
& =\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} d s_{\mathbb{I}} m_{l}(s) \star_{l} S_{R}^{-1}(s, T) S_{L}^{-1}\left(s_{0}, T\right) h_{\epsilon} \\
& =\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} d s_{\mathbb{I}} m_{l}(s) \star_{l}\left[S_{L}^{-1}\left(s_{0}, T\right)-S_{R}^{-1}(s, T)\right] \star_{l}\left(s_{0}-s\right)^{-\star_{l}} h_{\epsilon} \\
& =\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} d s_{\mathbb{I}} m_{l}(s) \star_{l} S_{L}^{-1}\left(s_{0}, T\right) \star_{l}\left(s_{0}-s\right)^{-\star_{l}} h_{\epsilon} \\
& -\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} d s_{\mathbb{I}} m_{l}(s) \star_{l} S_{R}^{-1}(s, T) \star_{l}\left(s_{0}-s\right)^{-\star_{l}} h_{\epsilon} .
\end{aligned}
$$

Since

$$
S_{L}^{-1}\left(s_{0}, T\right) \star_{l}\left(s_{0}-s\right)^{-\star_{l}}=\left(s_{0}-s\right)^{-\star_{r}} \star_{r} S_{L}^{-1}\left(s_{0}, T\right)
$$

where the $\star$-multiplication is taken with respect to $s$ on the right-hand side and is taken with respect to $s_{0}$ on the left-hand side (see Remark (2.4), we have

$$
\begin{aligned}
\tilde{y}= & \int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} d s_{\mathbb{I}} m_{l}(s) \star_{l}\left[\left(s_{0}-s\right)^{-\star_{r}}\right] x_{\epsilon} \\
& -\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} d s_{\mathbb{I}} m_{l}(s) \star_{l} S_{R}^{-1}(s, T) \star_{l}\left(s_{0}-s\right)^{-\star_{l}} h_{\epsilon} \\
= & 2 \pi i m_{l}\left(s_{0}\right) x_{\epsilon}-\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} d s_{\mathbb{I}} m_{l}(s) \star_{l} S_{R}^{-1}(s, T) \star_{l}\left(s_{0}-s\right)^{-\star_{l}} h_{\epsilon},
\end{aligned}
$$

by the Cauchy integral formula on slices. The function $m_{l}(s) \star_{l} S_{R}^{-1}(s, T)$ is a continuous operator-valued function on $\left.\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)$, while $\left(s_{0}-s\right)^{-\star_{l}}$ is continuous on $\left.\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)$. Hence, we have for the last integral

$$
\left\|\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} d s_{\mathbb{I}} m_{l}(s) \star_{l} S_{R}^{-1}(s, T) \star_{l}\left(s_{0}-s\right)^{-\star_{l}} h_{\epsilon}\right\| \rightarrow 0
$$

as $\epsilon \rightarrow 0$. Since $\left\|m_{l}\left(s_{0}\right) x_{\epsilon}\right\|=\left|m_{l}\left(s_{0}\right)\right| \neq 0$, we obtain that the vector

$$
\tilde{y}=\int_{\partial\left(\Gamma\left(\mathcal{J}_{0}\right) \cap \mathbb{C}_{\mathbb{I}}\right)} d s_{\mathbb{I}} m_{l}(s) \star_{l} S_{R}^{-1}(s, T) x_{\epsilon}
$$

is nonzero for all $\epsilon>0$, and hence $\mathscr{N}_{L, \mathbb{R}}$, and thus $\mathscr{N}$, are nontrivial.
Lemma 5.3. Let $T=A+B$, where $A$ is normal and $B$ is in the Schatten class for some integer $k>1$. Assume that $\Pi_{0, S}(T)=\emptyset$, and assume that $\sigma_{S}(A)$ contains the axially symmetric completion for an exposed arc $\mathcal{J}$. Let $s_{0} \in \tilde{\mathcal{J}} \cap \mathbb{C}_{\mathbb{I}}$ and $L$ be any closed bounded line segment starting from $s_{0}$ and not being tangent to $\tilde{\mathcal{J}} \cap \mathbb{C}_{\mathbb{I}}$. Moreover, assume that $L \cap \sigma_{S}(A)=\left\{s_{0}\right\}$. Then there exists a constant $K$ such that for all $s \in L \backslash\left\{s_{0}\right\}$ we have

$$
\left\|Q_{s}(T)\right\| \leq \exp \left(K\left|[s]-\left[s_{0}\right]\right|^{-2 k-2}\right)
$$

Proof. By Weyl's theorem 2.13 we know that $\Pi_{0, S}(T)=\emptyset$ means that $\sigma_{S}(T) \subset$ $\sigma_{S}(A)$. Consider the slice $\mathbb{C}_{\mathbb{I}}$ where $\mathbb{I} \in \mathbb{S}$ is arbitrary but fixed. Take an open disk $\mathcal{D} \subset \mathbb{C}_{\mathbb{I}}$ such that $\mathcal{D} \cap \sigma_{S}(A)=\tilde{\mathcal{J}} \cap \mathbb{C}_{\mathbb{I}}$. Here $\mathcal{J} \cap \mathbb{C}_{\mathbb{I}}$ divides $\mathcal{D}$ into two simply connected domains whose boundaries are simple closed Jordan curves. Let $L$ be a closed bounded line segment starting from $s_{0}$, not being tangent to $\mathcal{J}$, and such that $L \cap \sigma(A)=\left\{s_{0}\right\}$. Consider $\mathcal{D}^{\prime}$ an auxiliary disk in the slice $\mathbb{C}_{\mathbb{I}}$ which is tangent to $\tilde{\mathcal{J}} \cap \mathbb{C}_{\mathbb{I}}$ at $s_{0}$ and is contained in the subdomain of $\mathcal{D}$ which meets $L$. Denote by $\mathcal{C}^{\prime}$ the boundary of $\mathcal{D}^{\prime}$.

We now define the function $\delta$ on $\rho(A)$ via

$$
\delta(s):=\delta_{k, \mathbb{I}}\left(Q_{S}(A)\left\{A+\left(1-s_{0}\right) \mathcal{I}, B\right\}\right)
$$

where $\{A, B\}$ denotes the anticommutator of $A$ and $B$, i.e., $\{A, B\}=A B+B A$, and $\delta_{k, \mathbb{I}}$ is as in Definition 4.4. Then $\delta$ is continuous in $s$ on $\rho(A)$, and the operator $Q_{S}(A)\left\{A+\left(1-s_{0}\right) \mathcal{I}, B\right\}$ belongs to the same Schatten class as $B$. Furthermore, we have

$$
Q_{S}(T)=Q_{S}(A)\left(1+Q_{S}(A)\left\{A+\left(1-s_{0}\right) \mathcal{I}, B\right\}\right)^{-1}
$$

In particular, this means that

$$
-1 \notin \sigma_{S}\left(Q_{S}(A)\right)\left(\left\{A+\left(1-s_{0}\right) \mathcal{I}, B\right\}\right)
$$

and the absolute convergence of $\delta_{k, \mathbb{I}}$ (Lemma 4.5(i)) implies that $\delta(s) \neq 0$.

Therefore, we have

$$
Q_{S}(T)=\left(\delta(s)^{-1}\right) Q_{S}(A) \delta(s)\left(1+Q_{S}(A)\left\{A+\left(1-s_{0}\right) \mathcal{I}, B\right\}\right)^{-1}
$$

Since we have to estimate $\left\|Q_{S}(T)\right\|$, we proceed with the estimates for each term in the above equation individually. Because $A$ is normal, we have

$$
\left\|Q_{S}(A)\right\| \leq \frac{1}{\operatorname{dist}\left([s], \sigma_{S}(A)\right)^{2}} \leq \frac{1}{\operatorname{dist}\left([s], \mathcal{C}^{\prime}\right)^{2}}
$$

Furthermore, we have

$$
|\delta(s)| \leq \exp \left(K_{1}\left\|Q_{S}(A)\left\{A+\left(1-s_{0}\right) \mathcal{I}, B\right\}\right\|_{k}^{k}\right) \leq \exp \left(K_{2}\|B\|_{k}^{k}\left\|Q_{S}(A)\right\|^{k}\right)
$$

with

$$
K_{2}=2 K_{1}\left\|A+\left(1-s_{0}\right) \mathcal{I}, B\right\|
$$

This leads to

$$
\delta(s) \leq\left(\frac{K_{2}}{\operatorname{dist}\left([s], \mathcal{C}^{\prime}\right)^{2 k}}\right)
$$

Now since $|\delta(s)|$ is continuous and strictly positive, there exists an analytic function $\alpha$ with $|\delta(s)|=\exp (\operatorname{Re} \alpha(s))$ and $\operatorname{Re} \alpha(s) \leq K_{2} / d\left(s, C^{\prime}\right)^{2 k}$. Therefore, there exists a constant $K_{3}$ such that

$$
|\alpha(s)| \leq K_{3}\left|s-z_{0}\right|^{-2 k-2}
$$

for $s \in \mathcal{D}^{\prime} \cap L$. Hence,

$$
\operatorname{Re} \alpha(s) \geq-K_{3}\left|s-z_{0}\right|^{-2 k-2}
$$

and, consequently, we obtain

$$
\left|\delta(s)^{-1}\right| \leq \exp \left(K_{3}\left|s-z_{0}\right|^{-2 k-2}\right)
$$

Furthermore, from Lemma 4.5(iv) we get

$$
\begin{aligned}
\left\|\delta(s)\left(1+Q_{S}(A)\left\{A+\left(1-s_{0}\right) \mathcal{I}, B\right\}\right)^{-1}\right\| & \left.\leq \exp \left(K_{4} \| Q_{S}(A)\left\{A+\left(1-s_{0}\right) \mathcal{I}, B\right\}\right) \|_{k}^{k}\right) \\
& \leq \exp \left(K_{5} \frac{\|B\|_{k}^{k}}{\operatorname{dist}\left([s], \sigma_{S}(A)\right)^{2 k}}\right)
\end{aligned}
$$

which leads to

$$
\begin{aligned}
\left\|Q_{S}(T)\right\| & =\left|\left(\delta(s)^{-} 1\right)\right|\left\|Q_{S}(A)\right\|\left\|\delta(s)\left(1+Q_{S}(A)\left\{A+\left(1-s_{0}\right) \mathcal{I}, B\right\}\right)^{-1}\right\| \\
& \leq \exp \left(K_{3}\left|s-s_{0}\right|^{-2 k-2}\right) \frac{1}{\operatorname{dist}\left([s], \sigma_{S}(A)\right)^{2}}\left(K_{5} \frac{\|B\|_{k}^{k}}{\operatorname{dist}\left([s], \sigma_{S}(A)\right)^{2 k}}\right)
\end{aligned}
$$

Now since $L$ is not tangent to $\tilde{\mathcal{J}} \cap \mathbb{C}_{\mathbb{I}}$, the term $\left|s-s_{0}\right| / \operatorname{dist}\left([s], \sigma_{S}(A)\right)$ is bounded for $s \in L$. Consequently, there exists a constant $K$ such that

$$
\left\|Q_{S}(T)\right\| \leq \exp \left(K\left|s-s_{0}\right|^{-2 k-2}\right)
$$

for $s \in L \cap \mathcal{D}^{\prime}$.
Theorem 5.4. If $T=A+B$, where $A$ is normal and $B \in S_{p}(J)$ for some $p \geq 1$, and if $\sigma_{S}(A) \cap \mathbb{C}_{\mathbb{I}}$ contains an exposed arc for all $\mathbb{I} \in \mathbb{S}$, then $T$ has a nontrivial hyperinvariant subspace.

Proof. Let $\tilde{\mathcal{J}} \cap \mathbb{C}_{\mathbb{I}}$ be the exposed arc for $\mathbb{I} \in \mathbb{S}$. By Weyl's theorem 2.13

$$
\sigma_{S}(A) \subset \sigma_{S}(T) \cup \Pi_{0, S}(A)
$$

Due to the fact that $A$ is normal on a separable space, we have $\Pi_{0, S}(A)$ being countable, and thus a dense subset of $\tilde{\mathcal{J}}$ is contained in $\sigma_{S}(T)$; that is to say, $\tilde{\mathcal{J}} \subset \sigma_{S}(T)$. This further implies that $T$ is not a multiple of the identity operator. Hence, if $\Pi_{0, S}(T) \neq \emptyset$, then $T$ has nontrivial hyperinvariant subspaces.

Suppose now that $\Pi_{0, S}(T)=\emptyset$. Again by Weyl's theorem $2.13 \sigma_{S}(T) \subset \sigma_{S}(A)$, and $\tilde{\mathcal{J}} \cap \mathbb{C}_{\mathbb{I}}$ is an exposed arc of $\sigma_{S}(T) \cap \mathbb{C}_{\mathbb{I}}$ for all $\mathbb{I} \in \mathbb{S}$. Now by Lemma 5.3 the $S$-resolvent set of $T$ satisfies the growth condition in Theorem 5.2 with $k=\lceil p\rceil$. From this the result follows.

Corollary 5.5. If $T=A+B$, where $A$ is normal, $B \in S_{p}(J)$ for some $p \geq 1$, $\sigma_{S}(T)$ contains more than one point, and for all $\mathbb{I} \in \mathbb{S}$ we have $\sigma_{S}(A) \cap \mathbb{C}_{\mathbb{I}}$ contained in a smooth Jordan arc, then $T$ has a nontrivial hyperinvariant subspace.

Proof. Let $\tilde{\mathcal{J}}$ be such that $\tilde{\mathcal{J}} \cap \mathbb{C}_{\mathbb{I}}$ is a smooth arc and such that $\sigma_{S}(A) \subset \tilde{\mathcal{J}}$. As in the above, one can assume that $\Pi_{0, S}(T) \neq \emptyset$, so $\sigma_{S}(T) \subset \tilde{\mathcal{J}}$. If $\sigma_{S}(T)$ is disconnected, the result follows from the Riesz decomposition theorem. Hence, we can assume that $\sigma_{S}(T)=\tilde{\mathcal{J}}^{\prime}$, where $\tilde{\mathcal{J}}^{\prime} \cap \mathbb{C}_{\mathbb{I}}$ is a nontrivial subarc of $\tilde{\mathcal{J}} \cap \mathbb{C}_{\mathbb{I}}$ for all $\mathbb{I} \in \mathbb{S}$. Again by Weyl's theorem 2.13] this result is a consequence of Theorem 5.4.

Corollary 5.6. If $T=A+B$, where $A$ is normal, $B \in S_{p}(J)$ for some $p \geq 1$, and for all $\mathbb{I} \in \mathbb{S}$ we have $\sigma_{S}(A) \cap \mathbb{C}_{\mathbb{I}}$ being contained in a smooth Jordan arc, then $T$ has a nontrivial hyperinvariant subspace.

Proof. By Corollary [5.5 we can assume that $\sigma_{S}(T)$ contains only one point. By an appropriated translation we can assume that $\sigma_{S}(T)=\{0\}$, in which case $T$ is a compact operator. By Weyl's theorem 2.13 we have $\sigma_{S}(A) \subset\{0\} \cup \Pi_{0, S}(A)$. If $A$ is not compact, then either $A$ has a nonzero eigenvalue of infinite multiplicity or the eigenvalues of $A$ have an accumulation point at some nonzero value. In either case there exits an $s \neq 0$ and an orthonormal set $\left\{x_{n}\right\}$ such that $s_{n} \rightarrow s$ and $\left(A^{2}-2 \operatorname{Re}\left(s_{n}\right) A+\left|s_{n}\right|^{2}\right) x_{n}=0$ for all $n \in \mathbb{N}$. Since $B$ is compact, $B x_{n} \rightarrow 0$, and it follows that

$$
\begin{aligned}
& \left\|\left((A+B)^{2}-2 \operatorname{Re}(s)(A+B)+|s|^{2}\right) x_{n}\right\| \\
& \quad=\left\|\left(A^{2}-2 \operatorname{Re}(s) A+|s|^{2}\right) x_{n}+\left(\{A, B\}+B^{2}-2 \operatorname{Re}(s) B\right) x_{n}\right\| \rightarrow 0
\end{aligned}
$$

so $s \in \Pi_{S}(T)$. This contradicts the condition that $\sigma_{S}(T)=\{0\}$, and thus $A$ is compact as well as $T=A+B$. Hence, since the operator $T$ is compact, it has a nontrivial invariant subspace.

Corollary 5.7. If $T-T^{*} \in S_{p}(J)$ for some $p \geq 1$, then $T$ has a nontrivial invariant subspace.

Proof. The result follows from Corollary 5.6 since

$$
2 T=\left(T+T^{*}\right)+\left(T-T^{*}\right)
$$

and $T+T^{*}$ is a Hermitian operator, so its $S$-spectrum is real valued.
Corollary 5.8. If $\sigma_{S}(T)$ contains more than one point and $\mathcal{I}-T^{*} T \in S_{p}(J)$ for some $p \geq 1$, then $T$ has a nontrivial hyperinvariant subspace.

Proof. If either $T$ or $T^{*}$ has a nonempty point $S$-spectrum, then the result is trivially true. Assume now that both $\Pi_{0, S}(T)$ and $\Pi_{0, S}\left(T^{*}\right)$ are empty. Now recall that the polar decomposition $T=U P$ for quaternionic operators holds. The partial isometry arising from the polar decomposition of $T$ is unitary; that is to say, $T=U P$, where $U$ is unitary and $P$ is positive. So we have $P^{2}=T^{+} T$, but $\mathcal{I}-P^{2}$ is a compact Hermitian operator, so $P$ is diagonal. We suppose that for some orthonormal basis $\left\{v_{n}\right\}_{n \in \mathbb{N}} P v_{v}=v_{n} p_{n}$, the right eigenvalues are also the point $S$-spectrum and we have

$$
\sum_{n \in \mathbb{N}}\left|1-p_{n}^{2}\right|^{p}<\infty
$$

but we also have

$$
\sum_{n \in \mathbb{N}}\left|1-p_{n}^{2}\right|^{p}=\sum_{n \in \mathbb{N}}\left|1-p_{n}\right|^{p}\left|1+p_{n}\right|^{p} \geq \sum_{n \in \mathbb{N}}\left|1-p_{n}\right|^{p}
$$

This means that $\mathcal{I}-P \in S_{p}(J)$ and that

$$
T=U P=U(\mathcal{I}-(\mathcal{I}-P))=U-U(\mathcal{I}-P)
$$

Since the $S$-spectrum of a unitary operator is contained in the unit sphere of the quaternions and $U(\mathcal{I}-P) \in S_{p}(J)$, the result follows from Corollary 5.6.

We finally have the following immediate consequence of the above results.
Corollary 5.9. Let $\mathcal{I}-T^{*} T \in S_{p}(J)$ for some $p \geq 1$. Then $T$ has a nontrivial invariant subspace.

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