

# Interacção e Concorrência 2016/17

## Bloco de acetatos 8

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(based on Luís S. Barbosa 2014/15 course Slides )

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# Motivation

## System's correctness wrt a specification

- equivalence checking (between two designs), through  $\sim$  and  $=$
- unsuitable to check properties such as

**can the system perform action  $\alpha$  followed by  $\beta$ ?**

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- The **Hennessy-Milner logic** (offered in mCRL2)
- The **modal  $\mu$ -calculus** (offered in mCRL2)

# The language

## Signatures

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## Formulas

$$\phi ::= p \mid \mathbf{tt} \mid \mathbf{ff} \mid \neg\phi \mid \phi_1 \wedge \phi_2 \mid \phi_1 \rightarrow \phi_2 \mid \langle m \rangle \phi \mid [m] \phi$$

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where  $p \in \text{PROP}$  and  $m \in \text{MOD}$

Disjunction ( $\vee$ ) and equivalence ( $\leftrightarrow$ ) are defined by abbreviation.

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- if there is only one modality in the signature (i.e., MOD is a singleton), write simply  $\diamond\phi$  and



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- if there is only one modality in the signature (i.e., MOD is a singleton), write simply  $\diamond\phi$  and
- the language has some redundancy: in particular modal connectives are **dual** (as quantifiers are in first-order logic):  
 $[m]\phi$  is equivalent to  $\neg\langle m\rangle\neg\phi$

# The language

## Semantics

A **model** for the language is a pair  $\mathcal{M} = \langle \mathcal{F}, V \rangle$ , where

- $\mathcal{F} = \langle W, \{R_m\}_{m \in \text{MOD}} \rangle$  is a **Kripke frame**, ie,
  - $W$  is a non empty set (of **states** or **worlds**)
  - $\{R_m\}_{m \in \text{MOD}}$  is a family of binary relations  $R_m \subseteq W \times W$ , for each modality symbol  $m \in \text{MOD}$ .
- $V : \text{PROP} \rightarrow \mathcal{P}(W)$  is a **valuation**.

## The language

Satisfaction: for a model  $\mathcal{M}$  and a point  $w$

$\mathcal{M}, w \models \mathbf{tt}$

$\mathcal{M}, w \not\models \mathbf{ff}$

$\mathcal{M}, w \models p$

iff  $w \in V(p)$

$\mathcal{M}, w \models \neg\phi$

iff  $\mathcal{M}, w \not\models \phi$

$\mathcal{M}, w \models \phi_1 \wedge \phi_2$

iff  $\mathcal{M}, w \models \phi_1$  and  $\mathcal{M}, w \models \phi_2$

$\mathcal{M}, w \models \phi_1 \rightarrow \phi_2$

iff  $\mathcal{M}, w \not\models \phi_1$  or  $\mathcal{M}, w \models \phi_2$

$\mathcal{M}, w \models \langle m \rangle \phi$

iff there exists  $v \in W$  st  $wR_mv$  and  $\mathcal{M}, v \models \phi$

$\mathcal{M}, w \models [m] \phi$

iff for all  $v \in W$  st  $wR_mv$  and  $\mathcal{M}, v \models \phi$

# The language

## Satisfaction

A formula  $\phi$  is

- **satisfiable in a model**  $\mathcal{M}$  if it is satisfied at some point of  $\mathcal{M}$
- **globally satisfied** in  $\mathcal{M}$  ( $\mathcal{M} \models \phi$ ) if it is satisfied at all points in  $\mathcal{M}$
- **valid** ( $\models \phi$ ) if it is globally satisfied in all models
- **a semantic consequence** of a set of formulas  $\Gamma$  ( $\Gamma \models \phi$ ) if for all models  $\mathcal{M}$  and all points  $w$ , if  $\mathcal{M}, w \models \Gamma$  then  $\mathcal{M}, w \models \phi$

# Examples

## Temporal logic

- $W$  is a set of instants
- there is a unique modality corresponding to the **transitive closure of the next-time relation**
- **origin**: Arthur Prior, an attempt to *deal with temporal information from the inside, capturing the situated nature of our experience and the context-dependent way we talk about it*

## Examples: Temporal logics with $\mathcal{U}$ and $\mathcal{S}$

$\mathcal{M}, w \models \phi \mathcal{U} \psi$  iff

there exists  $v \in W$  such that  $(w, v) \in R$  and  $\mathcal{M}, v \models \psi$ , and for all  $u \in W$  such that  $(w, u) \in R$  and  $(u, v) \in R$  one has  $\mathcal{M}, u \models \phi$

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there exists a  $v \in W$  such that  $(v, w) \in R$  and  $\mathcal{M}, v \models \psi$  and, for all  $u$  such that  $(v, u) \in R$  and  $(u, w) \in R$  one has  $\mathcal{M}, u \models \phi$

- note the  $\exists\forall$  qualification pattern: these operators are neither diamonds nor boxes.
- helpful to express **guarantee** properties, e.g., **some event will happen, and a certain condition will hold until then**
- ... a plethora of temporal logics: **LTL**, **CTL**, **CTL\***

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Process logic (**Hennesy-Milner logic**)

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Assuming the underlying LTS  $\mathcal{F} = \langle \mathbb{P}, \{p \xrightarrow{K} p' \mid K \subseteq \text{Act}\} \rangle$  as the modal frame, satisfaction is abbreviated as

$$\begin{aligned} p \models \langle K \rangle \phi & \quad \text{iff} \quad \exists_{q \in \{p' \mid p \xrightarrow{a} p' \wedge a \in K\}} \cdot q \models \phi \\ p \models [K] \phi & \quad \text{iff} \quad \forall_{q \in \{p' \mid p \xrightarrow{a} p' \wedge a \in K\}} \cdot q \models \phi \end{aligned}$$

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- $\phi_4 =$  *A car on service is not inactive*
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## Process logic: typical properties

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- **inevitability of  $a$** :  $\langle - \rangle \mathbf{tt} \wedge [-a] \mathbf{ff}$
- **progress**:  $\langle - \rangle \mathbf{tt}$
- **deadlock or termination**:  $[-] \mathbf{ff}$
- satisfaction decided by unfolding the definition of  $\models$ : no need to compute the **transition graph**



# Hennessey-Milner logic

... propositional logic with **action** modalities

## Syntax

$$\phi ::= \mathbf{tt} \mid \mathbf{ff} \mid \phi_1 \wedge \phi_2 \mid \phi_1 \vee \phi_2 \mid \langle K \rangle \phi \mid [K] \phi$$

Semantics:  $E \models \phi$

$$E \models \mathbf{tt}$$

$$E \not\models \mathbf{ff}$$

$$E \models \phi_1 \wedge \phi_2 \quad \text{iff} \quad E \models \phi_1 \quad \wedge \quad E \models \phi_2$$

$$E \models \phi_1 \vee \phi_2 \quad \text{iff} \quad E \models \phi_1 \quad \vee \quad E \models \phi_2$$

$$E \models \langle K \rangle \phi \quad \text{iff} \quad \exists_{F \in \{E' \mid E \xrightarrow{a} E' \wedge a \in K\}} . F \models \phi$$

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## Example

$$Sem =^{df} get.put.Sem$$

$$P_i =^{df} \overline{get}.c_i.\overline{put}.P_i$$

$$S =^{df} (Sem \mid (\mid_{i \in I} P_i)) \setminus \{get, put\}$$

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- $Sem \models [put] \mathbf{ff}$  also holds, because

$$T = \{Sem' \mid Sem \xrightarrow{put} Sem'\} = \emptyset.$$

Hence  $\forall F \in T . F \models \mathbf{ff}$  becomes trivially true.

- The only action initially permited to  $S$  is  $\tau$ :  $\models [-\tau] \mathbf{ff}$ .

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- Afterwards,  $S$  can engage in any of the critical events  $c_1, c_2, \dots, c_i$ :  
 $[\tau] \langle c_1, c_2, \dots, c_i \rangle \mathbf{tt}$
- After the semaphore initial synchronization and the occurrence of  $c_j$  in  $P_j$ , a new synchronization becomes inevitable:  
 $S \models [\tau] [c_j] (\langle - \rangle \mathbf{tt} \wedge [-\tau] \mathbf{ff})$

## Exercise

Verify:

$$\neg \langle a \rangle \phi = [a] \neg \phi$$

$$\neg [a] \phi = \langle a \rangle \neg \phi$$

$$\langle a \rangle \mathbf{ff} = \mathbf{ff}$$

$$[a] \mathbf{tt} = \mathbf{tt}$$

$$\langle a \rangle (\phi \vee \psi) = \langle a \rangle \phi \vee \langle a \rangle \psi$$

$$[a] (\phi \wedge \psi) = [a] \phi \wedge [a] \psi$$

$$\langle a \rangle \phi \wedge [a] \psi \Rightarrow \langle a \rangle (\phi \wedge \psi)$$

## Exercise

Formalise each of the following properties:

- 1 The occurrence of  $a$  and  $b$  is impossible.
- 2 The occurrence of  $a$  followed by  $b$  is impossible.
- 3 Only the occurrence of  $a$  is possible.
- 4 Once  $a$  occurred,  $b$  or  $c$  may occur.
- 5 After  $a$  occurred followed by  $b$ ,  $c$  may occur.
- 6 Once  $a$  occurred,  $b$  or  $c$  may occur but not both.
- 7  $a$  cannot occur before  $b$ .
- 8 There is only an initial transition labelled by  $a$ .



## Exercise

Consider the following processes and enumerate for each of them the properties they verify:

①  $E_1 =^{df} a.b.\mathbf{0}$

②  $E_2 =^{df} a.c.\mathbf{0}$

③  $E =^{df} E_1 + E_2$

④  $F =^{df} a.(b.\mathbf{0} + c.\mathbf{0})$

⑤  $G =^{df} E + F$

## Exercise

Specify a LTS such that the following modal properties hold simultaneously in its initial state:

- $\langle a \rangle \langle b \rangle \langle c \rangle \mathbf{tt} \wedge \langle c \rangle \mathbf{tt}$
- $\langle a \rangle \langle b \rangle ([a] \mathbf{ff} \wedge [c] \mathbf{ff} \wedge [b] \mathbf{ff})$
- $\langle a \rangle \langle b \rangle (\langle a \rangle \mathbf{tt} \wedge [c] \mathbf{ff})$

## Exercise

Consider the following specification of a CNC program:

$$Start =^{df} fw.Go + stop.\mathbf{0}$$

$$Go =^{df} fw.bk.bk.Start + right.left.bk.Start$$

Formalise the following properties:

- 1 After *fw* another *fw* is immediately possible
- 2 After *fw* followed by *right*, *left* is possible but *bk* is not.
- 3 Action *fw* is the only one initially possible
- 4 The third action of process *Start* is not *fw*.

## Hennessy-Milner with regular modalities

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$$\alpha := K \mid K \cup K \mid K \cap K$$

for  $K \subseteq A$ . As above we represent

- the set  $A$  with  $-$
- the set  $A \setminus \{a\}$  with  $-a$

## Regular modalities

$$R := \epsilon \mid \alpha \mid R.R \mid R + R \mid R^*$$

# Hennessy-Milner with regular modalities

## interpretation of regular modalities

- $\langle R_1 + R_2 \rangle true = \langle R_1 \rangle true \vee \langle R_2 \rangle true$   
 $[R_1 + R_2] true = [R_1] true \vee [R_2] true$
- $\langle R_1.R_2 \rangle true = \langle R_1 \rangle \langle R_2 \rangle true$   
 $[R_1.R_2] true = [R_1][R_2] true$

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- As long as no *error* happens, a deadlock will not occur.

$$[(-error)^*]\langle - \rangle \mathbf{tt}$$

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$$[-^*.a]\langle -^*. (b \cup c) \rangle \mathbf{tt}$$



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$$[-^*.a]\langle -^*. (b \cup c) \rangle \mathbf{tt}$$

- Whenever an *a* action happens, it must always be possible to do a *b* after that, although doing the *b* can infinitely be postponed.

$$[-^*.a.(-b)^*]\langle -^*.b \rangle \mathbf{tt}$$

# A denotational semantics

**Idea:** associate to each formula  $\phi$  the **set** of processes that makes it true

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$$\|\mathbf{tt}\| = \mathbb{P}$$

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$$\|\phi_1 \wedge \phi_2\| = \|\phi_1\| \cap \|\phi_2\|$$

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$$\|[K]\phi\| = \|[K]\|(\|\phi\|)$$

$$\|\langle K \rangle \phi\| = \|\langle K \rangle\|(\|\phi\|)$$

## $\| [K] \|$ and $\| \langle K \rangle \|$

Just as  $\wedge$  corresponds to  $\cap$  and  $\vee$  to  $\cup$ , modal logic combinators correspond to **unary functions** on sets of processes:

$$\| [K] \| (X) = \{ F \in \mathbb{P} \mid \text{if } F \xrightarrow{a} F' \wedge a \in K \text{ then } F' \in X \}$$

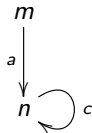
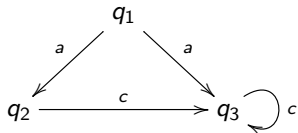
$$\| \langle K \rangle \| (X) = \{ F \in \mathbb{P} \mid \exists F' \in X, a \in K . F \xrightarrow{a} F' \}$$

### Note

These combinators perform a **reduction to the previous state** indexed by actions in  $K$

$\| [K] \|$  and  $\| \langle K \rangle \|$

## Example



$$\| \langle a \rangle \| \{q_2, n\} = \{q_1, m\}$$

$$\| [a] \| \{q_2, n\} = \{q_2, q_3, m, n\}$$

## A denotational semantics

$$E \models \phi \text{ iff } E \in \|\phi\|$$

Example:  $\mathbf{0} \models [-] \mathbf{ff}$



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because

$$\begin{aligned}\|[-] \mathbf{ff}\| &= \|[-]\|(\|\mathbf{ff}\|) \\ &= \|[-]\|(\emptyset) \\ &= \{F \in \mathbb{P} \mid \text{if } F \xrightarrow{x} F' \wedge x \in \text{Act} \text{ then } F' \in \emptyset\} \\ &= \{\mathbf{0}\}\end{aligned}$$

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$$\begin{aligned} \|\langle - \rangle \mathbf{tt}\| &= \|\langle - \rangle\|(\|\mathbf{tt}\|) \\ &= \|\langle - \rangle\|(\mathbb{P}) \\ &= \{F \in \mathbb{P} \mid \exists_{F' \in \mathbb{P}, a \in K} . F \xrightarrow{a} F'\} \\ &= \mathbb{P} \setminus \{\mathbf{0}\} \end{aligned}$$

# A denotational semantics

## Complement

Any property  $\phi$  divides  $\mathbb{P}$  into two disjoint sets:

$$\|\phi\| \text{ and } \mathbb{P} - \|\phi\|$$

The **characteristic formula** of the complement of  $\|\phi\|$  is  $\phi^c$ :

$$\|\phi^c\| = \mathbb{P} - \|\phi\|$$

where  $\phi^c$  is defined inductively on the formulae structure:

$$\begin{aligned} \mathbf{tt}^c &= \mathbf{ff} & \mathbf{ff}^c &= \mathbf{tt} \\ (\phi_1 \wedge \phi_2)^c &= \phi_1^c \vee \phi_2^c \\ (\phi_1 \vee \phi_2)^c &= \phi_1^c \wedge \phi_2^c \\ (\langle a \rangle \phi)^c &= [a] \phi^c \end{aligned}$$

... but **negation** is not explicitly introduced in the logic.

## Exercise

Compute

①  $\|\langle a \rangle \langle - \rangle \mathbf{tt}\|$

②  $\|[a] \langle - \rangle \mathbf{tt} \wedge [b] [-] \mathbf{ff}\|$

③  $\|[a] \langle - \rangle \mathbf{tt} \vee [b] [-] \mathbf{ff}\|$

# Modal Equivalence

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## Examples

$$a.b.\mathbf{0} + a.c.\mathbf{0} \simeq_{\Gamma} a.(b.\mathbf{0} + c.\mathbf{0})$$

for  $\Gamma = \{ \langle x_1 \rangle \langle x_2 \rangle \dots \langle x_n \rangle \mathbf{tt} \mid x_i \in Act \}$

# Modal Equivalence

For each (finite or infinite) set  $\Gamma$  of formulae,

$$E \simeq F \iff E \simeq_{\Gamma} F \text{ for every set } \Gamma \text{ of well-formed formulae}$$



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$$E \sim F \Rightarrow E \simeq F$$

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## Lemma

$$E \sim F \Rightarrow E \simeq F$$

## Note

the converse of this lemma does not hold, e.g. let

- $A =^{df} \sum_{i \geq 0} A_i$ , where  $A_0 =^{df} \mathbf{0}$  and  $A_{i+1} =^{df} a.A_i$
- $A' =^{df} A + K$ ,  $K = a.K$

$$A \approx A' \text{ but } A \not\simeq A'$$

# Modal Equivalence

Theorem [Hennessy-Milner, 1985]

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for **image-finite** processes.

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Image-finite processes

$E$  is **image-finite** iff  $\{F \mid E \xrightarrow{a} F\}$  is **finite** for every action  $a \in Act$

# Modal Equivalence

Theorem [Hennessy-Milner, 1985]

$$E \sim F \Leftrightarrow E \simeq F$$

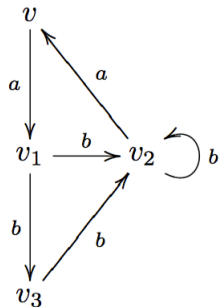
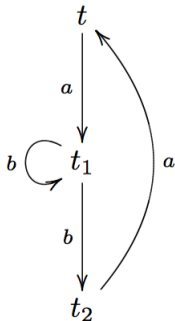
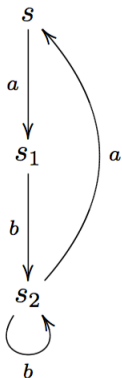
for **image-finite** processes.

proof

$\Rightarrow$  : by induction of the formula structure

$\Leftarrow$  : show that  $\simeq$  is itself a bisimulation, by contradiction

## Exercise



Show that states  $s$ ,  $t$  and  $v$  are not bisimilar and determine the modal properties which distinguish between them.

## Exercise

Consider processes  $E \stackrel{df}{=} a.(b.\mathbf{0} + c.\mathbf{0})$  e  $F \stackrel{df}{=} a.b.\mathbf{0} + a.c.\mathbf{0}$ .  
Propose a formula  $\phi$  in  $\mathcal{M}$  valid in  $E$  but false in  $F$ .

## Exercise

Let  $E$  be a process. A formula  $\phi$  is said to be *characteristic* of  $E$  iff

$$\forall F \in \mathbb{P} . F \models \phi \text{ sse } F \sim E$$

Note that a process verifies the characteristic formula of  $E$  iff it is strongly bisimilar to  $E$ .

Determine the *characteristic* formula of process  $x.0$ .



## Exercise

Consider processes below and write down a formula in  $\mathcal{M}$  valid in  $R$  but not in  $S$ .

$$E \stackrel{df}{=} b.c.\mathbf{0} + b.d.\mathbf{0} \quad (1)$$

$$F \stackrel{df}{=} E + b.(c.\mathbf{0} + d.\mathbf{0}) \quad (2)$$

$$R \stackrel{df}{=} a.E + a.F \quad (3)$$

$$S \stackrel{df}{=} a.F \quad (4)$$

## Exercise

In general, parallel composite in process algebra fails to be idempotent.

- 1 Making  $E =^{df} a.b.E$ , formalise a property in  $\mathcal{M}$  to distinguish between  $E$  and  $E \mid E$ .
- 2 In some cases idempotency holds. Build a bisimulation to witness equivalence  $E \sim E \mid E$  when  $E$  is  $E =^{df} \sum_{x \in K} x.E$ , for any  $K \subseteq Act - \{\tau\}$ . Would this remain true for  $Act$ ?